

Math 2270-6

Notes of 11/12/19

- Tying up loose end from yesterday. Suppose

$$A = [\mathbf{a}_1 \quad \mathbf{a}_2 \quad \dots \quad \mathbf{a}_n]$$

is $m \times n$ and

$$A = QR$$

where

$$Q = [\mathbf{q}_1 \quad \mathbf{q}_2 \quad \dots \quad \mathbf{q}_n]$$

is $m \times n$ with orthonormal columns and R is $n \times n$ upper triangular.

- Then the first k columns of A span the same space as the first k columns of Q .
- In principle, Q can be computed by applying the Gram-Schmidt process to the columns of A .
- Since

$$Q^T Q = I_n$$

with I_n being the $n \times n$ identity matrix we can compute R by

$$R = Q^T A.$$

6.5 Least Squares Problems

- We start with a somewhat elaborate example. You may have seen it before in Calculus, and we'll use Calculus notation. Then we will generalize it, turn it into a Linear Algebra Problems, and change the notation to Linear Algebra notation.
- On your calculator there may be a “linear regression” button.
- What does it do?
- It computes a line that approximates a set of specified points in an optimal sense. The points may represent, for example, inaccurately measured values.
- Suppose we are given the points $(2, 2)$, $(5, 5)$, and $(7, 5)$. There is no line that passes through all three points, but we can represent them approximately by a line, as shown in Figure 1.
- How do we find that line?
- We use three points in this example for computational simplicity, there could be many more points!
- Lets present our line as

$$y = L(x) = mx + b$$

as usual.

- The key idea is to minimize the sum of squares:

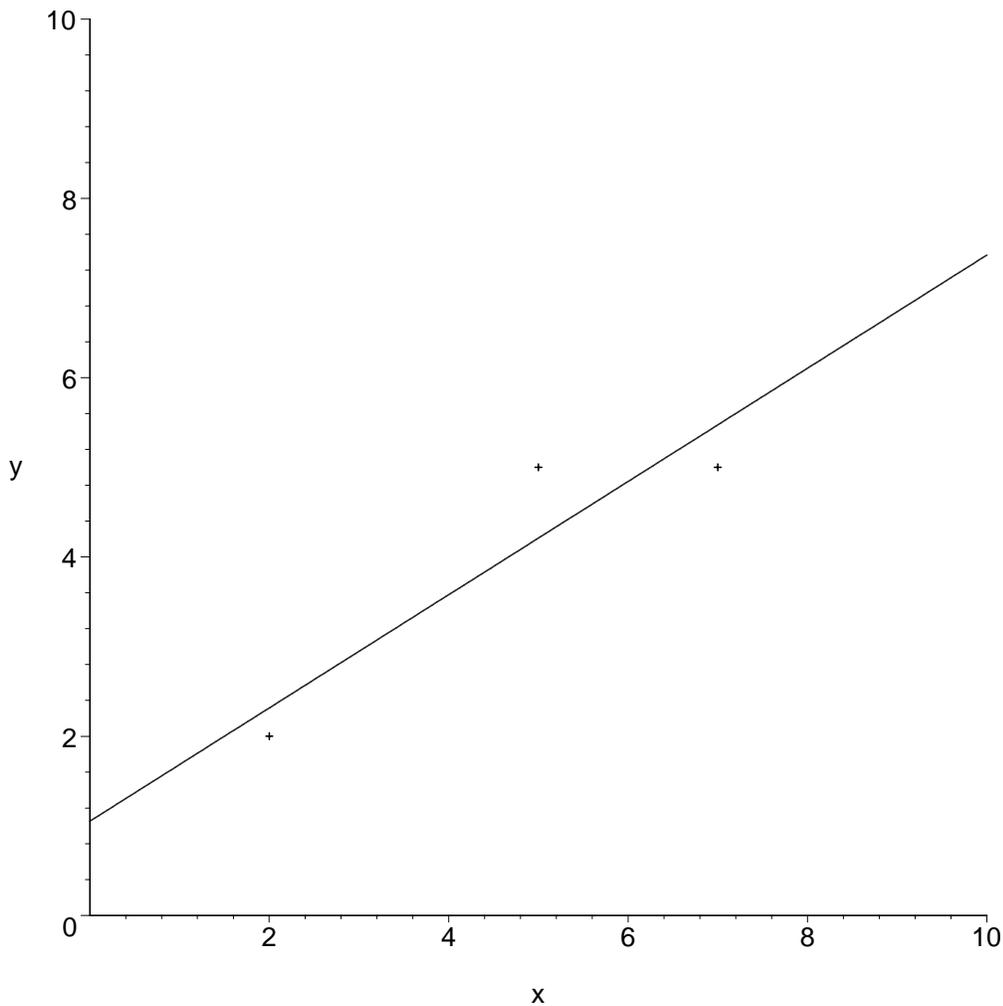


Figure 1. 3 points and a line.

$$\begin{aligned}
 F(m, b) &= (2 - (2m + b))^2 \\
 &+ (5 - (5m + b))^2 \\
 &+ (5 - (7m + b))^2 = \min
 \end{aligned} \tag{1}$$

- Thus we want to minimize a function of two variables. In Calculus we learned that the way to do is to compute the gradient, set it to zero, and then solve the resulting system.

$$\nabla F = \begin{bmatrix} F_m(m, b) \\ F_b(m, b) \end{bmatrix} = \mathbf{0}.$$

- In our case, since we are minimizing a sum of squares, we will get a **linear system**.
- We could expand the squares in (1) and then differentiate, or differentiate first. The second approach is better. We get

$$\begin{aligned} F_m(m, b) &= -2(2 - (2m + b)) \times 2 \\ &\quad - 2(5 - (5m + b)) \times 5 \\ &\quad - 2(5 - (7m + b)) \times 7 = 0 \end{aligned}$$

i.e.,

$$-2[2 \times 2 + 5 \times 5 + 5 \times 7 - m(2 \times 2 + 5 \times 5 + 7 \times 7) - b(2 + 5 + 7)] = 0.$$

This becomes

$$78m + 14b = 64. \quad (2)$$

- similarly,

$$\begin{aligned} F_b(m, b) &= -2(2 - (2m + b)) \\ &\quad - 2(5 - (5m + b)) \\ &\quad - 2(5 - (7m + b)) = 0 \end{aligned}$$

i.e.,

$$-2[2 \times 2 + 5 \times 5 + 5 \times 7 - m(2 \times 2 + 5 \times 5 + 7 \times 7) - b(2 + 5 + 7)] = 0.$$

This gives the equation

$$14m + 3b = 12 \quad (3)$$

- The equations (2) and (3) are two linear equations in the 2 unknowns m and b . Solving them gives

$$m = \frac{12}{19} \quad \text{and} \quad b = \frac{20}{19}.$$

- The points and the line

$$y = \frac{12}{19}x + \frac{20}{19}$$

are shown in Figure 1.

- We might be given hundreds of points. The calculation just indicated would become quite tedious. So let's do the problem in general.
- Suppose we are given n points (x_i, y_i) , $i = 1, \dots, n$.
- We want to find m and b such that

$$y_i \approx mx_i + b, \quad i = 1, \dots, n \quad (4)$$

- To that end we pick m and b so as to minimize

$$F(m, b) = \sum_{i=1}^n (y_i - (mx_i + b))^2 = \min.$$

- As usual we compute the partial derivatives and set them equal to zero:

$$\frac{\partial}{\partial m} F(m, b) = -2 \sum_{i=1}^n (y_i - (mx_i + b))x_i = 0$$

and

$$\frac{\partial}{\partial b} F(m, b) = -2 \sum_{i=1}^n (y_i - (mx_i + b)) = 0$$

- Dividing by -2, distributing the sums, and collecting the m and b terms on one side and the constant terms on the other side gives the linear system

$$m \sum_{i=1}^n x_i^2 + b \sum_{i=1}^n x_i = \sum_{i=1}^n x_i y_i$$

$$m \sum_{i=1}^n x_i + b \sum_{i=1}^n 1 = \sum_{i=1}^n y_i$$

- This is the linear system your calculator solves when you press the linear regression button.
- In our previous example we have the data

x_i y_i

2 2

5 5

7 5

and get

$$\begin{aligned}\sum x_i^2 &= 2^2 + 5^2 + 7^2 &= 78 \\ \sum x_i &= 2 + 5 + 7 &= 14 \\ \sum 1 &= 1 + 1 + 1 &= 3 \\ \sum x_i y_i &= 2 \times 2 + 5 \times 5 + 7 \times 5 &= 64 \\ \sum y_i &= 2 + 5 + 5 &= 12\end{aligned}$$

which leads to the same linear system

$$\begin{aligned}78m + 14b &= 64 \\ 14m + 3b &= 12\end{aligned}$$

as before.

- Of course, instead of a linear function you could use a quadratic function. You'll get 3 equations in 3 unknowns.
- The concept we discussed is much more general. You could consider polynomials of degree greater than 2 or even non-polynomial functions.
- Let's take a different tack. Suppose all the points actually are on the lines. Then we would have the equations

$$y_i = mx_i + b, \quad i = 1, \dots, n \quad (5)$$

- We can write this as the linear system

$$\begin{bmatrix} x_1 & 1 \\ x_2 & 1 \\ \vdots & \vdots \\ x_n & 1 \end{bmatrix} \begin{bmatrix} m \\ b \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$$

- However, minimizing the sum of squares of the difference between the left and right sides of the equations (5) in this case gives the **Least Squares Problem**

$$\left\| \begin{bmatrix} x_1 & 1 \\ x_2 & 1 \\ \vdots & \vdots \\ x_n & 1 \end{bmatrix} \begin{bmatrix} m \\ b \end{bmatrix} - \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix} \right\|^2 = \min$$

- Also notice that the previously obtained linear system

$$m \sum_{i=1}^n x_i^2 + b \sum_{i=1}^n x_i = \sum_{i=1}^n x_i y_i$$

$$m \sum_{i=1}^n x_i + b \sum_{i=1}^n 1 = \sum_{i=1}^n y_i$$

can be rewritten in terms of our matrix notation as

$$\begin{bmatrix} x_1 & 1 \\ x_2 & 1 \\ \vdots & \vdots \\ x_n & 1 \end{bmatrix}^T \begin{bmatrix} x_1 & 1 \\ x_2 & 1 \\ \vdots & \vdots \\ x_n & 1 \end{bmatrix} \begin{bmatrix} m \\ b \end{bmatrix} = \begin{bmatrix} x_1 & 1 \\ x_2 & 1 \\ \vdots & \vdots \\ x_n & 1 \end{bmatrix}^T \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$$

Least Squares in General

- Let's take a fresh start (and also make a change in notation). Suppose we have an overdetermined linear system

$$A\mathbf{x} = \mathbf{b} \quad (6)$$

- Here A is $m \times n$, \mathbf{x} is in \mathbb{R}^n , \mathbf{b} is in \mathbb{R}^m , and $m \geq n$ (and typically, $m > n$).
- Usually, the system (6) will not have a solution. In that case, the next best thing is to solve the alternative problem

$$\|A\mathbf{x} - \mathbf{b}\| = \min$$

- In other words (the words of our textbook), we want to find a vector $\hat{\mathbf{x}}$ in \mathbb{R}^n such that

$$\|\mathbf{b} - A\hat{\mathbf{x}}\| \leq \|\mathbf{b} - A\mathbf{x}\|$$

for all \mathbf{x} in \mathbb{R}^n .

- The textbook calls such an $\hat{\mathbf{x}}$ a **Least Squares Solution** of

$$A\mathbf{x} = \mathbf{b}.$$

- I would call it a solution of

$$\|A\mathbf{x} - \mathbf{b}\| = \min.$$



We will soon see that \hat{x} is unique if the columns of A are linearly independent.

- First: **Theorem 13** (p. 363) The set of least square solutions of $A\mathbf{x} = \mathbf{b}$ coincides with the nonempty set of solutions of the **normal equations**

$$A^T A\mathbf{x} = A^T \mathbf{b}.$$

- Before seeing why this is true, let's go back to our introductory example.
- There

$$A = \begin{bmatrix} 2 & 1 \\ 5 & 1 \\ 7 & 1 \end{bmatrix} \quad \text{and} \quad \mathbf{b} = \begin{bmatrix} 2 \\ 5 \\ 5 \end{bmatrix}.$$

- We get

$$A^T A\mathbf{x} = \begin{bmatrix} 78 & 14 \\ 14 & 3 \end{bmatrix} \begin{bmatrix} m \\ b \end{bmatrix} = \begin{bmatrix} 64 \\ 12 \end{bmatrix}$$

- This is the same set of equations as before, with the same solution.
- So let's see why Theorem 14 is true

- We can tell more than Theorem 13!
- **Theorem 14** (p. 365) Let A be an $m \times n$ matrix. The following statements are logically equivalent. (This means they are either all true or all false):
 - a. The equation $A\mathbf{x} = \mathbf{b}$ has a unique least square solution for each \mathbf{b} in \mathbb{R}^m .
 - b. The columns of A are linearly independent.
 - c. The matrix $A^T A$ is invertible.

Using the QR factorization