

Math 2270-1
Review

9/10/19

standard matrix of a linear transformation

$$T: \mathbb{R}^n \rightarrow \mathbb{R}^m$$

$$y = T(x)$$

$$y \in \mathbb{R}^m \quad x \in \mathbb{R}^n$$

$$T \text{ linear } \vdash T(u+v) = T(u) + T(v)$$

$$T(cu) = cT(u)$$

$$T(x) = Ax \quad A \text{ } m \times n$$

$$A = [a_1 \dots a_n] \quad x = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}$$

$$Ax = \sum_{i=1}^n x_i a_i$$

$$a_i = T(e_i)$$

$$e_i = \begin{bmatrix} 0 \\ \vdots \\ 0 \\ 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix} \leftarrow i\text{-th place}$$

$$e_i \in \mathbb{R}^n$$

$$T(x) = T\left(\sum_{i=1}^n x_i e_i\right) \quad x = \sum_{i=1}^n x_i e_i$$

$$= \sum_{i=1}^n T(x_i e_i)$$

$$= \sum_{i=1}^n x_i T(e_i)$$

$$= \sum_{i=1}^n x_i a_i$$

$$= Ax$$

$$m = n = 2$$

$$T\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right) = \begin{bmatrix} 1 \\ 2 \end{bmatrix} \quad T\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} 3 \\ 4 \end{bmatrix}$$

$$T\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}\right) = \begin{bmatrix} 1 & 3 \\ 2 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$$T\left(\begin{bmatrix} 1 \\ 2 \end{bmatrix}\right) = \begin{bmatrix} 3 \\ 4 \end{bmatrix}$$

$$T\left(\begin{bmatrix} 1 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} 5 \\ 6 \end{bmatrix}$$

$$T(x) = Ax$$

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 3 \\ 4 \end{bmatrix} \quad \begin{bmatrix} 1 \\ 1 \end{bmatrix} \quad \begin{bmatrix} a+b \\ c+d \end{bmatrix} = \begin{bmatrix} 5 \\ 6 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{bmatrix}$$

$$T(x) = Ax \quad x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$Ax = x_1 \begin{bmatrix} 1 \\ 3 \\ 5 \end{bmatrix} + x_2 \begin{bmatrix} 2 \\ 4 \\ 6 \end{bmatrix}$$

$$Ax = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

$$x_1 + 2x_2 = 1$$

$$3x_1 + 4x_2 = 1$$

$$5x_1 + 6x_2 = 1$$

$$x_2 = 1 \quad x_1 = -1$$

$$\begin{bmatrix} 1 & 2 & 1 \\ 3 & 4 & 1 \\ 5 & 6 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 1 \\ 0 & -2 & -2 \\ 0 & -4 & -4 \end{bmatrix}$$

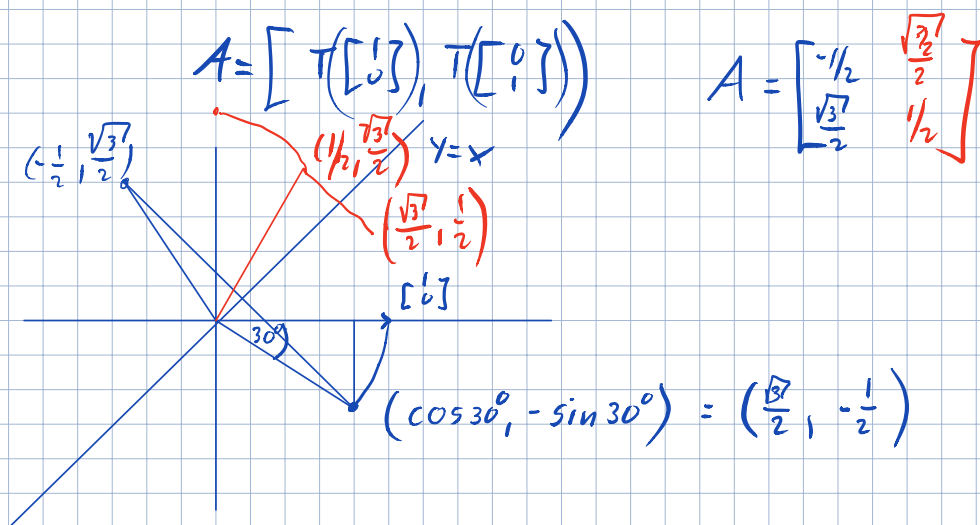
$$\rightarrow \begin{bmatrix} 1 & 2 & 1 \\ 0 & -2 & -2 \\ 0 & 0 & 0 \end{bmatrix} \begin{array}{l} x_1 + 2 = 1 \rightarrow x_1 = -1 \\ -2x_2 = -2 \\ x_2 = 1 \end{array}$$

$$T(x) = Ax = b$$

$$A_{\text{ret}} \begin{bmatrix} \cdot & \cdot \\ \cdot & \cdot \\ \cdot & \cdot \end{bmatrix} \begin{bmatrix} \cdot \\ \cdot \\ \cdot \end{bmatrix} = \begin{bmatrix} b_1 \\ \cdot \\ b_m \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 0 & 0 & 0 & 0 \\ 3 & 4 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$T(x)$: rotate x clockwise by 30°
and then reflect in $x=y$



Domain set of all inputs

Range (Image) set of all outputs

codomain $\mathbb{R}^n \supset \text{Range}$

$T: \mathbb{R}^n \rightarrow \mathbb{R}^m$
 $A = [a_1, a_2, \dots, a_n]$

 linear $T(x) = Ax$

 $A_{m \times n}$

domain: \mathbb{R}^n

codomain: \mathbb{R}^m

range: $= \text{span}\{a_1, \dots, a_n\}$

$S = \{v_1, \dots, v_n\}$ linearly independent

$$\text{if } \sum_{i=1}^n c_i v_i = 0 \Rightarrow c_i = 0 \quad i=1, \dots, n$$

S linearly dependent

$$3v_1 + \dots = 0$$

$$v_1 = \frac{1}{3}(- + \dots)$$

$$\{v_1, v_2, v_3\} \quad 3v_1 + 2v_2 \overset{+0v_3}{=} 0$$

$$v_1 = -\frac{2}{3}v_2$$

$$v_2 = -\frac{3}{2}v_1$$

Ex.: $\left\{ \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 4 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$

$$Ax = b$$

$$Ay = b$$

$$y - x \neq 0$$

$$A(y - x) = 0$$