

# Math 2270-1

## Notes of 10/21/2019

### 5.1 Eigenvalues and Eigenvectors

- We'll start with an example. Suppose we have a population of individuals (think mice, for example) with 4 cohorts, those 0, 1, 2, 3 units of time (years) old. Every year all those 3 years old die. Of the other three cohorts, half survive. The population reproduces. Cohort 2 (1 year old) produces  $2/3$  of their number in offspring, cohort 3 produce  $4/3$  their number, and cohort 4 produce  $8/3$  their number. Is there a population that is stable, which means that the total number of individuals and the age distribution do not change over time.
- Suppose the population is given by

$$\mathbf{p} = \begin{bmatrix} p_1 \\ p_2 \\ p_3 \\ p_4 \end{bmatrix}$$

where  $p_i$  is the number of individuals  $i - 1$  years old.

- We are looking for a vector  $\mathbf{p}$  such that

$$\begin{bmatrix} 0 & 2/3 & 4/3 & 8/3 \\ 1/2 & 0 & 0 & 0 \\ 0 & 1/2 & 0 & 0 \\ 0 & 0 & 1/2 & 0 \end{bmatrix} \begin{bmatrix} p_1 \\ p_2 \\ p_3 \\ p_4 \end{bmatrix} = \begin{bmatrix} p_1 \\ p_2 \\ p_3 \\ p_4 \end{bmatrix}.$$

- 

It is easy to check that

$$\mathbf{p} = \begin{bmatrix} 8 \\ 4 \\ 2 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 2/3 & 4/3 & 8/3 \\ 1/2 & 0 & 0 & 0 \\ 0 & 1/2 & 0 & 0 \\ 0 & 0 & 1/2 & 0 \end{bmatrix} \begin{bmatrix} 8 \\ 4 \\ 2 \\ 1 \end{bmatrix}$$

solves the problem.

- Here is a modification of this problem. Suppose cohorts 2 and 3 produce twice their number in offspring, and cohorts 1 and 4 produce no offspring at all. We would want a vector  $\mathbf{p}$  such that

$$\begin{bmatrix} 0 & 2 & 2 & 0 \\ 1/2 & 0 & 0 & 0 \\ 0 & 1/2 & 0 & 0 \\ 0 & 0 & 1/2 & 0 \end{bmatrix} \begin{bmatrix} p_1 \\ p_2 \\ p_3 \\ p_4 \end{bmatrix} = \begin{bmatrix} p_1 \\ p_2 \\ p_3 \\ p_4 \end{bmatrix}.$$

- There is no such vector! However, using suitable software (matlab) we can check that within the given accuracy

$$\begin{bmatrix} 0 & 2 & 2 & 0 \\ 1/2 & 0 & 0 & 0 \\ 0 & 1/2 & 0 & 0 \\ 0 & 0 & 1/2 & 0 \end{bmatrix} \begin{bmatrix} 9.081 \\ 3.811 \\ 1.599 \\ 0.671 \end{bmatrix} = 1.915 \begin{bmatrix} 9.081 \\ 3.811 \\ 1.599 \\ 0.671 \end{bmatrix}$$

- So here we have a population that is stable in the sense that its age distribution does not change. However, the total population grows by a little more than 19 percent each year.



note that if  $\mathbf{p}$  is a population that satisfies our linear system then of course any scalar multiple of  $\mathbf{p}$  also satisfies the equation.

- **Definition:** An **eigenvector** of a square ( $n \times n$ ) matrix  $A$  is a **non-zero** vector  $\mathbf{x}$  such that

$$A\mathbf{x} = \lambda\mathbf{x}$$

for some scalar  $\lambda$ .  $\lambda$  is called the **eigenvalue** of  $A$  corresponding to the eigenvector  $\mathbf{x}$ .  $\mathbf{x}$  is an eigenvector corresponding to the eigenvalue  $\lambda$ .

- The pair  $(\lambda, \mathbf{x})$  is sometimes called an **eigen-pair** of  $A$ .
- The word “eigen” is German for “own”. The eigenvalues of  $A$  are numbers “owned” by  $A$ , they are the matrix’s very own numbers. With an eigenvector, the matrix acts like a number. Multiplying with the matrix is equivalent to multiplying with the eigenvalue.



Note that any non-zero scalar multiple of an eigenvector is also an eigenvector, with the same eigenvalue.



Why do we require the eigenvector to be non-zero?



In one word, what is the major difference between the two problems

$$A\mathbf{x} = \mathbf{b} \quad \text{and} \quad A\mathbf{x} = \lambda\mathbf{x}?$$

- Some examples:
- What are eigenvalues and eigenvectors of the identity matrix?
- What are eigenvalues and eigenvectors of the zero matrix?
- What are eigenvalues and eigenvectors of

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix} ?$$

- More insight can be gained by writing

$$A\mathbf{x} = \lambda\mathbf{x}$$

as

$$A\mathbf{x} - \lambda\mathbf{x} = (A - \lambda I)\mathbf{x} = \mathbf{0}.$$

- Any eigenvector is a non-trivial solution of the homogeneous linear system

$$(A - \lambda I)\mathbf{x} = \mathbf{0}.$$

- Every eigenvector is in the nullspace of  $A - \lambda I$ .
- Every non-zero vector in the nullspace of  $A - \lambda I$  is an eigenvector of  $A$ .
- A square homogeneous linear system has a non-trivial solution if and only if the coefficient matrix is singular.



thus  $\lambda$  is an eigenvalue of  $A$  if and only if  $A - \lambda I$  is singular.



Upshot: one more characterization of singularity. A square matrix  $A$  is singular if and only if 0 is an eigenvalue of  $A$ . It is invertible if and only if all eigenvalues of  $A$  are non-zero.

- Suppose  $\mathbf{x}_i, i = 1, \dots, m$  are eigenvectors corresponding to the same eigenvalue  $\lambda$ . Then

any (non-zero) linear combination of the eigenvectors is also an eigenvector:

$$A \sum_{i=1}^m \alpha_i \mathbf{x}_i = \sum_{i=1}^n \alpha_i A \mathbf{x}_i = \sum_{i=1}^n \alpha_i \lambda \mathbf{x}_i = \lambda \sum_{i=1}^n \alpha_i \mathbf{x}_i.$$

- Thus, if we add the zero vector to the set of eigenvectors corresponding to a specific eigenvalue, that set is a linear space, the nullspace of  $A - \lambda I$ . That space is also called the **eigenspace of  $A$  corresponding to  $\lambda$** .
- Important example: The eigenvalues of a triangular matrix are the diagonal entries, because if  $\lambda$  is on the diagonal then  $A - \lambda I$  is a triangular matrix with at least one zero entry on the diagonal, and is thus singular.

- We are now approaching the question of how to find eigenvalues and eigenvectors.



Row operations do not preserve eigenvalues and eigenvectors!

- Examples
- $\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$  versus  $\begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$ .

- $\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$  versus  $\begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$ .

- We need something else ...



- Observation:  $\lambda$  is an eigenvalue if and only if  $A - \lambda I$  is singular.
- Recall that a matrix is singular if and only if its determinant is zero. Thus we get the key result:

$$\lambda \text{ is an e.v.} \quad \Leftrightarrow \quad \det(A - \lambda I) = 0.$$

- This is worth some study ....