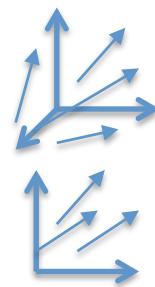


Handout 8

Microsoft Mathematics: a software for 3D visualization – useful tool

<http://www.microsoft.com/en-us/download/details.aspx?id=15702>

Definition: Vector is mathematical object that specify length/magnitude and direction. We denote a vector by putting a little over on the top, or sometime in books by using bold font. $\vec{a}, \vec{u}, \vec{v}$ or $\mathbf{a}, \mathbf{u}, \mathbf{v}$. We write a vector as a list of numbers in angle brackets $\langle x, y \rangle$ or $\langle x, y, z \rangle$.



A vector from point A to point B is denoted as \vec{AB} and sketched as a line segment with an arrow points in the direction of the vector. However, the vector considered as a numerical quantity that doesn't represent the locations of A and B, but the location of point B relative to A as if A were the coordinate origin. Thus, vectors are position-less and therefore:

Definition: two vectors considered equivalent if their magnitude\length and direction is equal, regardless the position. Similarly $\langle x_1, y_1, z_1 \rangle = \langle x_2, y_2, z_2 \rangle$
 $\langle x_1, y_1 \rangle = \langle x_2, y_2 \rangle$ iff $x_1 = x_2, y_1 = y_2, z_1 = z_2$.

Definition: A vector from point $A(x_1, y_1, z_1)$ ($\vec{A}(x_1, y_1, z_1)$) to point $B(x_2, y_2, z_2)$ ($\vec{B}(x_2, y_2, z_2)$) is denoted as $\vec{AB} = \langle x_2 - x_1, y_2 - y_1, z_2 - z_1 \rangle$ ($\vec{AB} = \langle x_2 - x_1, y_2 - y_1 \rangle$)

Vector Arithmetic

Let $\vec{a} = \langle a_1, a_2 \rangle, \vec{b} = \langle b_1, b_2 \rangle, \vec{c} = \langle c_1, c_2, c_3 \rangle, \vec{d} = \langle d_1, d_2, d_3 \rangle$ be a vectors and k a constant. In order to distinct vectors and numbers we will call k a **scalar**.

Definition: The length or a magnitude of 2D, 3D vectors \vec{a}, \vec{c} is defined by

$|\vec{a}| = \sqrt{a_1^2 + a_2^2}$ and $|\vec{c}| = \sqrt{c_1^2 + c_2^2 + c_3^2}$ respectively (don't confuse with absolute value).

Definition: The **unit vector** is a vector with magnitude\length equal 1.

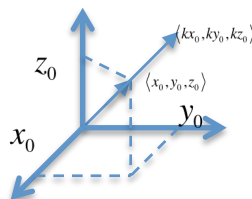
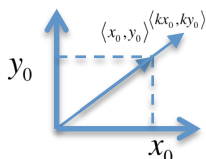
Definition: Scalar Multiplication defined as $k\vec{a} = \langle ka_1, ka_2 \rangle$ and $k\vec{c} = \langle kc_1, kc_2, kc_3 \rangle$.

If $k < 0$ then the vector change direction. Note also that

$$|k\vec{a}| = \sqrt{k^2 a_1^2 + k^2 a_2^2} = |k| \sqrt{a_1^2 + a_2^2} = |k| |\vec{a}| \quad \text{and}$$

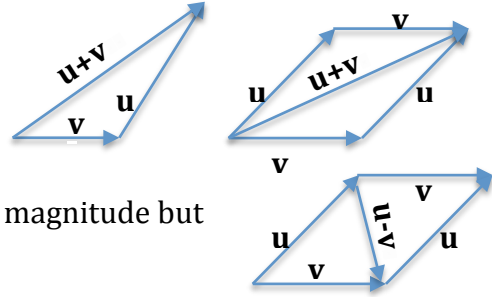
$$|k\vec{c}| = \sqrt{k^2 c_1^2 + k^2 c_2^2 + k^2 c_3^2} = |k| \sqrt{c_1^2 + c_2^2 + c_3^2} = |k| |\vec{c}|$$

Thus scalar multiplication scales (either stretch or squeeze) vector magnitude\length.



Note: Every vector \mathbf{u} can be converted into a unit vector by multiplying it by very special scalar equal to reciprocal of it's magnitude: $\left| \frac{1}{|\vec{u}|} \vec{u} \right| = \left| \frac{\vec{u}}{|\vec{u}|} \right| = \frac{|\vec{u}|}{|\vec{u}|} = 1$.

Definitino: Vector Addition defined as $\vec{a} + \vec{b} = \langle a_1 + b_1, a_2 + b_2 \rangle$ and $\vec{c} + \vec{d} = \langle c_1 + d_1, c_2 + d_2, c_3 + d_3 \rangle$. The addition of vectors can be understood geometrically as as a Triangle Law or a Parallelogram Law, which are illustrated below.



Definitino: Vector Subtraction defined by $\vec{u} - \vec{v} = \vec{u} + (-\vec{v})$ where $-\vec{v}$ is the vector with the same magnitude but opposite direction \vec{v} .

Properties of vectors:

1. $\vec{a} + \vec{b} = \vec{b} + \vec{a}$
2. $(\vec{a} + \vec{b}) + \vec{c} = \vec{a} + (\vec{b} + \vec{c})$
3. $\vec{a} + \vec{0} = \vec{a}$
4. $\vec{a} + (-\vec{a}) = \vec{0}$
5. $k(\vec{a} + \vec{b}) = k\vec{a} + k\vec{b}$
6. $(k + m)\vec{a} = k\vec{a} + m\vec{a}$
7. $(km)\vec{a} = k(m\vec{a})$

Standard basis (i-j-k notations)

We define 3 very important vectors, called a **Standard Basis**:

$\mathbf{i} = \langle 1, 0, 0 \rangle$; $\mathbf{j} = \langle 0, 1, 0 \rangle$; $\mathbf{k} = \langle 0, 0, 1 \rangle$ in 3D or equivalently $\mathbf{i} = \langle 1, 0 \rangle$; $\mathbf{j} = \langle 0, 1 \rangle$ in 2D.

Theorem: Every vector can be expressed as a sum of vectors of the standard basis as following

$$\langle a_1, a_2, a_3 \rangle = a_1 \langle 1, 0, 0 \rangle + a_2 \langle 0, 1, 0 \rangle + a_3 \langle 0, 0, 1 \rangle = a_1 \mathbf{i} + a_2 \mathbf{j} + a_3 \mathbf{k}$$

$$\langle a_1, a_2 \rangle = a_1 \langle 1, 0 \rangle + a_2 \langle 0, 1 \rangle = a_1 \mathbf{i} + a_2 \mathbf{j}$$