

4.5 The Chain Rule (11.5)

Recall: Chain Rule for $y=f(x)$, $x=g(t)$: $\frac{dy}{dt} = \frac{dy}{dx} \frac{dx}{dt}$

Thm: Chain Rule for $z=f(x,y)$, $x(t)=g(t)$, $y(t)=h(t)$: $\frac{dz}{dt} = \frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt}$

$$\begin{aligned}\frac{dz}{dt} &= \frac{d}{dt} f(g(t), h(t)) = \lim_{\delta \rightarrow 0} \frac{f(g(t+\delta), h(t+\delta)) - f(g(t), h(t))}{\delta} = \\ &= \lim_{\delta \rightarrow 0} \frac{f(g(t) + \Delta^{\delta} g, h(t) + \Delta^{\delta} h) - f(g(t), h(t))}{\delta} = \\ &= \lim_{\delta \rightarrow 0} \frac{\cancel{f(g(t), h(t))} + f_x(g(t), h(t))\Delta^{\delta} g + f_y(g(t), h(t))\Delta^{\delta} h - \cancel{f(g(t), h(t))}}{\delta} \\ &= f_x(g(t), h(t)) \lim_{\delta \rightarrow 0} \frac{\Delta^{\delta} g}{\delta} + f_y(g(t), h(t)) \lim_{\delta \rightarrow 0} \frac{\Delta^{\delta} h}{\delta} = \frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt}\end{aligned}$$

Ex 1. Find $\frac{dz}{dt}$ for $z = 3xy^2 - 4x^3y$, $x = e^t$, $y = \sin t$

$$\frac{dz}{dt} = (3y^2 - 12x^2y)e^t + (6xy - 4x^3)\cos t = (3\sin^2 t - 12e^{2t} \sin t)e^t + (6e^t \sin t - 4e^{3t})\cos t$$

Ex 2. Let $z_x = -z_y$. Find $y(x)$ such that $u(x) = z(x, y(x))$ is constant.

The derivative of a constant function is equal zero, therefore

$$u'(x) = \frac{dz}{dx} = \frac{\partial z}{\partial x} \frac{dx}{dx} + \frac{\partial z}{\partial y} \frac{dy}{dx} = \frac{\partial z}{\partial x} + \frac{\partial z}{\partial y} \frac{dy}{dx} = z_x + z_y \frac{dy}{dx} = -z_y + z_y \frac{dy}{dx} = z_y \left(\frac{dy}{dx} - 1 \right) = 0$$

Thus either one is true $z_y = 0$ or $\frac{dy}{dx} = 1$.

If $z_y = 0$ then $z_x = -z_y = 0$ and therefore, z is constant function regardless of $y(x)$.

Otherwise, we got $\frac{dy}{dx} = 1 \Rightarrow y(x) = \int \frac{dy}{dx} dx = \int 1 \cdot dx = x + C$.

Thm: Chain Rule for $z=f(x,y)$, $x(t)=g(s,t)$, $y(t)=h(s,t)$:

$$\frac{\partial z}{\partial t} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial t} \quad \frac{\partial z}{\partial s} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial s}$$

Ex 3. $z = xy + \sin(xy)$, $x = \cos st$, $y = \sin st$

$$\begin{aligned}\frac{\partial z}{\partial s} &= \frac{\partial z}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial s} = -(y + y \cos xy)t \sin st + (x + x \cos xy)t \cos st = \\ &= -(1 + \cos(\cos st \sin st))t \sin^2 st + (1 + \cos(\cos st \sin st))t \cos^2 st \\ \frac{\partial z}{\partial t} &= \frac{\partial z}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial t} = -(y + y \cos xy)s \sin st + (x + x \cos xy)s \cos st = \\ &= -(1 + \cos(\cos st \sin st))s \sin^2 st + (1 + \cos(\cos st \sin st))s \cos^2 st\end{aligned}$$

Ex 4. $z = f(x, y)$ $x = r \cos \theta, y = r \sin \theta$

$$x = r \cos \theta, y = r \sin \theta \Rightarrow r(x, y) = \sqrt{x^2 + y^2}; \theta(x, y) = \arctan \frac{y}{x}$$

$$\frac{\partial z}{\partial x} = \frac{\partial z}{\partial r} \frac{\partial r}{\partial x} + \frac{\partial z}{\partial \theta} \frac{\partial \theta}{\partial x} = \frac{\partial z}{\partial r} \frac{x}{\sqrt{x^2 + y^2}} - \frac{\partial z}{\partial \theta} \frac{y}{x^2 + y^2} = \frac{\partial z}{\partial r} \frac{r \cos \theta}{r} - \frac{\partial z}{\partial \theta} \frac{r \sin \theta}{r^2} = \frac{\partial z}{\partial r} \cos \theta - \frac{1}{r} \frac{\partial z}{\partial \theta} \sin \theta$$

$$\frac{\partial z}{\partial y} = \frac{\partial z}{\partial r} \frac{\partial r}{\partial y} + \frac{\partial z}{\partial \theta} \frac{\partial \theta}{\partial y} = \frac{\partial z}{\partial r} \frac{y}{\sqrt{x^2 + y^2}} + \frac{\partial z}{\partial \theta} \frac{x}{x^2 + y^2} = \frac{\partial z}{\partial r} \frac{r \sin \theta}{r} + \frac{\partial z}{\partial \theta} \frac{r \cos \theta}{r^2} = \frac{\partial z}{\partial r} \sin \theta + \frac{1}{r} \frac{\partial z}{\partial \theta} \cos \theta$$

Ex 5. $z = f(x, y), x = s - t, y = s + t$

$$\frac{\partial z}{\partial s} = \frac{\partial z}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial s} = \frac{\partial z}{\partial x} + \frac{\partial z}{\partial y}, \quad \frac{\partial z}{\partial t} = \frac{\partial z}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial t} = -\frac{\partial z}{\partial x} + \frac{\partial z}{\partial y}$$

$$(z_x)^2 - (z_y)^2 = (z_x - z_y)(z_x + z_y) = z_s z_t$$

Thm: Implicit differentiation

1) Given equation $F(x, y(x)) = 0$, one differentiate both sides with respect to x to get

$$F_y \underbrace{\frac{\partial y}{\partial x}}_{=1} + F_x \underbrace{\frac{\partial x}{\partial x}}_{=1} = 0 \text{ then solve it for } \frac{dy}{dx} = -\frac{F_x}{F_y}$$

2) Similarly, given $F(x, y, z(x, y)) = 0$:

a. Differentiating with respect to x gives $F_x \underbrace{\frac{\partial x}{\partial x}}_{=1} + F_y \underbrace{\frac{\partial y}{\partial x}}_{=0} + F_z \underbrace{\frac{\partial z}{\partial x}}_{=0} = 0 \Rightarrow z_x = -\frac{F_x}{F_z}$

b. Differentiating with respect to y gives $F_x \underbrace{\frac{\partial x}{\partial y}}_{=0} + F_y \underbrace{\frac{\partial y}{\partial y}}_{=1} + F_z \underbrace{\frac{\partial z}{\partial y}}_{=0} = 0 \Rightarrow z_y = -\frac{F_y}{F_z}$

Ex 6. $x + \cos xy + \sin xz = 0$

$$1 - y \sin xy + z \cos xz + z_x \cos xz = 0 \Rightarrow z_x = -\frac{1 - y \sin xy + z \cos xz}{x \cos xz} = -\frac{F_x}{F_z}$$

$$-x \sin xy + xz_y \cos xz = 0 \Rightarrow z_y = \frac{x \sin xy}{x \cos xz} = -\frac{F_y}{F_z}$$

4.6 Directional Derivatives and the Gradient Vector (11.6)

The derivative of $f(x,y,z)$ with respect to x, y or z are also called the derivative in the direction of x, y, z . We can generalize the idea and to find the derivative of the function in direction of any line $(x,y) = (at + x_0, bt + y_0)$.

Def: The (Directional) Derivative of a function $f(x,y)$ in a direction of a unit vector $\vec{u} = \langle a, b \rangle$ is given by $D_{\vec{u}}f(x_0, y_0) = \lim_{h \rightarrow 0} \frac{f(x_0 + ah, y_0 + bh) - f(x_0, y_0)}{h}$ if the limit exists.

Thm: $D_{\vec{u}}f(x_0, y_0) = f_x(x_0, y_0)a + f_y(x_0, y_0)b$

Proof: Define $g(t) = f(at + x_0, bt + y_0)$. Note that $g'(t) = f_x(at + x_0, bt + y_0)a + f_y(at + x_0, bt + y_0)b$ at $t = 0$ gives $g'(0) = D_{\vec{u}}f(x_0, y_0)$ therefore $D_{\vec{u}}f(x_0, y_0) = g'(0) = f_x(x_0, y_0)a + f_y(x_0, y_0)b$.

Def: Gradient vector of a function of 2 variables is defined as

$$\vec{\nabla}f(x, y) = \langle f_x(x, y), f_y(x, y) \rangle = \frac{\partial f}{\partial x} \mathbf{i} + \frac{\partial f}{\partial y} \mathbf{j}$$

$$\text{Similarly } \vec{\nabla}f(x, y, z) = \langle f_x(x, y, z), f_y(x, y, z), f_z(x, y, z) \rangle = \frac{\partial f}{\partial x} \mathbf{i} + \frac{\partial f}{\partial y} \mathbf{j} + \frac{\partial f}{\partial z} \mathbf{k}$$

$$\text{And } \vec{\nabla}f(x_1, \dots, x_n) = \langle f_1(x_1, \dots, x_n), \dots, f_n(x_1, \dots, x_n) \rangle$$

Def: Another definition of directional derivative:

$$D_{\langle a, b \rangle}f(x, y) = \vec{\nabla}f(x, y) \cdot \langle a, b \rangle$$

$$D_{\langle a, b, c \rangle}f(x, y, z) = \vec{\nabla}f(x, y, z) \cdot \langle a, b, c \rangle$$

$$D_{\langle y_1, \dots, y_n \rangle}f(x_1, \dots, x_n) = \vec{\nabla}f(x_1, \dots, x_n) \cdot \langle y_1, \dots, y_n \rangle$$

Def: Yet another way to define directional derivative: let $f : \mathbb{R}^n \rightarrow \mathbb{R}$ be a real valued function with a vector space domain \mathbb{R}^n , i.e. $f(\vec{x}) \in \mathbb{R}$. Thus, the directional derivative is given by

$$D_{\vec{u}}f(\vec{x}) = \lim_{h \rightarrow 0} \frac{f(\vec{x} + h\vec{u}) - f(\vec{x})}{h}$$

Ex 7. Let $f(x, y, z) = xy \cos z$ and let $\vec{u} = \langle 1, 2, 3 \rangle$:

$$D_{\vec{u}}f(1, 2, 0) = \langle y \cos z, x \cos z, -xy \sin z \rangle_{(x, y, z)=(1, 2, 0)} \cdot \langle 1, 2, 3 \rangle = \langle 2, 1, -2 \rangle \cdot \langle 1, 2, 3 \rangle = 2 + 2 - 6 = -2$$

Thm: The maximum of a directional derivative at given point occurs when the vector u has the same direction as the gradient vector.

Proof: $D_{\vec{u}}f = \vec{\nabla}f \cdot \vec{u} = |\vec{\nabla}f| |\vec{u}| \cos \theta$, where θ is the angle between $\vec{\nabla}f$ and $|\vec{u}|$. Since $\cos \theta$ reaches maximum has the maximum 1, which occurs at $\theta = 0$, in other words when the vector u has the same direction as the gradient vector.