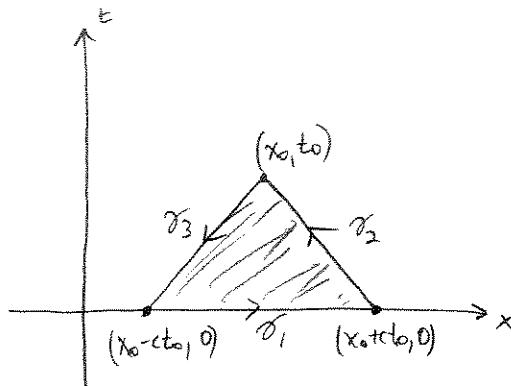


①



Let Ω denote the shaded triangle domain, and let $\partial = \partial_1 + \partial_2 + \partial_3$ be its boundary. Suppose we are given the vector field

$$\vec{G} = \langle M, N \rangle = \langle u_t, c^2 u_x \rangle. \text{ Green's Theorem states}$$

$$\iint_{\Omega} (N_x - M_t) dA = \oint_{\partial\Omega} M dx + N dt = \int_a^b \vec{b}(\vec{r}(t)) \cdot \vec{r}'(t) dt,$$

where $\vec{r}(t)$ is any parameterization of $\partial\Omega = \partial$.

We begin with the right-hand side:

$$\oint_{\partial} M dx + N dt = \oint_{\partial_1} M dx + N dt + \oint_{\partial_2} M dx + N dt + \oint_{\partial_3} M dx + N dt.$$

For ∂_1 : A parameterization of ∂_1 is $\vec{r}_1(t) = \langle x_0 - ct_0, 0 \rangle + \tau \langle 2ct_0, 0 \rangle$
 $0 \leq \tau \leq 1$

$$\begin{aligned} \text{So } \oint_{\partial_1} M dx + N dt &= \int_0^1 \langle u_t(\vec{r}_1(t)), c^2 u_x(\vec{r}_1(t)) \rangle \cdot \langle 2ct_0, 0 \rangle dt \\ &= \int_0^1 2ct_0 u_t(x_0 - ct_0 + \tau 2ct_0, 0) dt \end{aligned}$$

$$\text{Let } v = x_0 - ct_0 + 2ct_0 \tau$$

$$dv = 2ct_0 d\tau$$

$$\begin{aligned} \Rightarrow \oint_{\partial_1} M dx + N dt &= \int_{x_0 - ct_0}^{x_0 + ct_0} 2ct_0 u_t(v, 0) \frac{dv}{2ct_0} \\ &= \int_{x_0 - ct_0}^{x_0 + ct_0} u_t(v, 0) dv \\ &= \int_{x_0 - ct_0}^{x_0 + ct_0} g(v) dv \end{aligned}$$

①

For γ_2 : A parameterization of γ_2 is:

$$\vec{r}_2(t) = \langle x_0 + (t-t_0, 0) \rangle + \tau \langle (-c, 1) \rangle, 0 \leq \tau \leq t.$$

$$\begin{aligned} \oint_{\gamma_2} M dx + N dy &= \int_0^{t_0} \langle u_t(\vec{r}_2(\tau)), c^2 u_x(\vec{r}_2(\tau)) \rangle \cdot \langle -c, 1 \rangle d\tau \\ &= \int_0^{t_0} [-c u_t(\vec{r}_2(\tau)) + c^2 u_x(\vec{r}_2(\tau))] d\tau \end{aligned}$$

$$= -c \int_0^{t_0} [u_t(x_0 + ct_0 - c\tau, \tau) - c u_x(x_0 + ct_0 - c\tau, \tau)] d\tau$$

$$\text{Now, } \frac{\partial}{\partial t} u(x_0 + ct_0 - c\tau, \tau) = u_t u_x + u_{tt}$$

$$\begin{aligned} \Rightarrow \oint_{\gamma_2} M dx + N dy &= -c \int_0^{t_0} \frac{\partial}{\partial t} u(x_0 + ct_0 - c\tau, \tau) d\tau \\ &= -c [u(x_0 + ct_0 - ct_0, t_0) - u(x_0 + ct_0, 0)] \end{aligned}$$

$$= -c [u(x_0, t_0) - f(x_0 + ct_0)]$$

For γ_3 : A parameterization of γ_3 is:

$$\vec{r}_3(t) = \langle x_0, t_0 \rangle + \tau \langle (-c, -1) \rangle \quad 0 \leq \tau \leq t.$$

$$\begin{aligned} \oint_{\gamma_3} M dx + N dy &= \int_0^t \langle u_t(\vec{r}_3(\tau)), c^2 u_x(\vec{r}_3(\tau)) \rangle \cdot \langle -c, -1 \rangle d\tau \\ &= \int_0^t [c u_t(\vec{r}_3(\tau)) - c^2 u_x(\vec{r}_3(\tau))] d\tau \\ &= c \int_0^t [u_t(x_0 - c\tau, t_0 - \tau) - c u_x(x_0 - c\tau, t_0 - \tau)] d\tau \\ &= c \int_0^t \frac{\partial}{\partial t} u(x_0 - c\tau, t_0 - \tau) d\tau \\ &= c u(x_0 - ct_0, t_0) \Big|_0^t \\ &= c [u(x_0 - ct_0, 0) - u(x_0, t_0)] \\ &= c [f(x_0 - ct_0) - u(x_0, t_0)] \end{aligned}$$

$$\text{Also, } \iint_{\Omega} (N_x - M_t) dA = \iint_{\Omega} (c^2 u_{xx} - u_{tt}) dA = \iint_{\Omega} -F dA = -\iint_{\Omega} F dA$$

Thus, by Green's Theorem,

$$\iint_{\Omega} (N_x - M_t) dA = \oint_{\partial\Omega} N dx + M dt$$

$$\begin{aligned} \Leftrightarrow -\iint_{\Omega} F dA &= \int_{x_0-ct_0}^{x_0+ct_0} g(v) dv - c [u(x_0, t_0) - f(x_0 + ct_0)] \\ &\quad + c [f(x_0 + ct_0) - u(x_0, t_0)] \\ &= c [f(x_0 + ct_0) + f(x_0 - ct_0)] - 2u(x_0, t_0) + \int_{x_0-ct_0}^{x_0+ct_0} g(x) dx. \end{aligned}$$

$$\Rightarrow 2u(x_0, t_0) = c [f(x_0 + ct_0) + f(x_0 - ct_0)] + \int_{x_0-ct_0}^{x_0+ct_0} g(x) dx + \iint_{\Omega} F dA$$

$$\Rightarrow u(x_0, t_0) = \frac{1}{2} [f(x_0 + ct_0) + f(x_0 - ct_0)] + \frac{1}{2c} \int_{x_0-ct_0}^{x_0+ct_0} g(x) dx + \iint_{\Omega} F dA.$$

- ② Let $\Omega \subset \mathbb{R}^n$ be an open domain, $f: \Omega \rightarrow \mathbb{R}$ continuous. Suppose that for all open balls $B(x_0, r) = \{x \in \mathbb{R}^n : \|x - x_0\| < r\}$ with $B(x_0, r) \subset \Omega$ we have $(*) \int_{B(x_0, r)} f(x) dV = 0$, prove $f(x) \equiv 0$ in Ω .

Proof: Assume for contradiction that $\exists x_0 \in \Omega$ s.t. $f(x_0) = m > 0$.

$$\begin{aligned} \text{Since } f \text{ is continuous, } (\forall \varepsilon > 0) (\exists \delta > 0) (\forall x \in \Omega) (x \in B(x_0, \delta)) \Rightarrow f(x) \in (f(x_0) - \varepsilon, f(x_0) + \varepsilon) \\ = (m - \varepsilon, m + \varepsilon). \end{aligned}$$

Suppose $\varepsilon = \frac{m}{2}$. then $(\exists \delta > 0) (\forall x \in \Omega) (x \in B(x_0, \delta) \Rightarrow f(x) \in (m, 3m/2))$, so $f(x) > m/2$ for all $x \in B(x_0, \delta)$. Hence

$$\int_{B(x_0, r)} f(x) dV \geq \int_{B(x_0, r)} m/2 dV = m/2 \int_{B(x_0, r)} dV = m/2 \text{Vol}(B(x_0, r)) > 0. \rightarrow$$

Now suppose $f(x_0) = -m$, where $m > 0$. Since f is continuous,
 $(\exists \delta > 0) (\forall x \in \Omega) (x \in B(x_0, \delta) \Rightarrow f(x) \in (-m - \frac{m}{2}, -m + \frac{m}{2}) = (-\frac{3m}{2}, -\frac{m}{2}))$.

In particular, if $x \in B(x_0, \delta)$, $f(x) < -\frac{m}{2}$. Thus

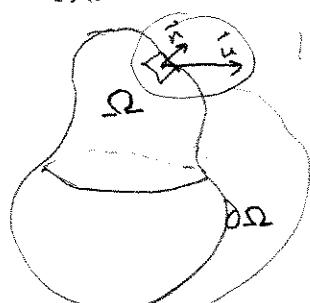
$$\int_{B(x_0, \delta)} f(x) dV \leq \int_{B(x_0, \delta)} -\frac{m}{2} dV = -\frac{m}{2} V(B(x_0, \delta)) < 0 \quad \rightarrow \blacksquare$$

③ Derive the Navier-Stokes Equations:

$$a) \nabla \cdot (\rho \vec{u}) + \rho_t = 0$$

$$b) \rho \vec{u}_t + \rho \vec{u} \cdot \nabla \vec{u} + \nabla p = \rho \vec{F}$$

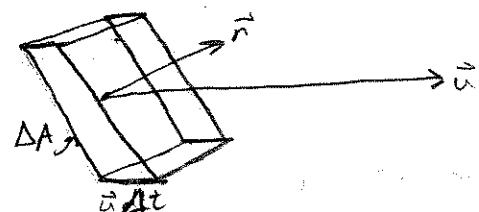
Soln: a) Consider a fixed domain $\Omega \subset \mathbb{R}^3$,



Let $\vec{u}(\vec{x}, t)$ be the velocity field at (\vec{x}, t)
 $\rho(\vec{x}, t)$ be the density ($\frac{\text{mass}}{\text{volume}}$) at (\vec{x}, t)

and (\vec{x}, t) denote Eulerian coordinates,

In order to determine the mass of the fluid passing through $\partial\Omega$, consider a small "piece" of $\partial\Omega$ with outward normal \vec{n} . The total mass that passed through this piece of surface in time Δt , given by the volume of this parallelepiped times the density, i.e.,



$$\begin{aligned} \Delta m &= (\text{Volume})(\text{density}) \\ &= \Delta A (\vec{u} \Delta t) \cdot \vec{n} \rho \end{aligned}$$

Dividing both sides by Δt and taking limits gives

$$\frac{dm}{dt} = \rho (\vec{u} \cdot \vec{n}) dA = (\rho \vec{u}) \cdot \vec{n} dA$$

The rate mass is going into Ω is given by

$$\frac{dm}{dt} = - \iint_{\partial\Omega} (\rho \vec{u}) \cdot \vec{n} dA = - \iint_{\Omega} \nabla \cdot (\rho \vec{u}) dV. \quad \text{①}$$

↑
divergence
theorem

On the other hand, the mass contained in Ω is given by:

$$M(t) = \iiint_{\Omega} \rho(\vec{x}, t) dV$$

Therefore $\frac{dm}{dt} = \frac{d}{dt} \iiint_{\Omega} \rho(\vec{x}, t) dV$

we can pass the derivative through the integrals, since Ω doesn't depend on t and we are integrating over the volume.

Thus $\frac{dm}{dt} = \iiint_{\Omega} \rho_t(\vec{x}, t) dV \quad \textcircled{2}$

Equating $\textcircled{1}$ and $\textcircled{2}$ we obtain the following:

$$-\iiint_{\Omega} \nabla \cdot (\rho \vec{u}) dV = \iiint_{\Omega} \rho_t(\vec{x}, t) dV$$

$$\Leftrightarrow \iiint_{\Omega} [\rho_t + \nabla \cdot (\rho \vec{u})] dV = 0$$

This is true for any open domain $\Omega \subset \mathbb{R}^3$, in particular, for every open ball in \mathbb{R}^3 . Hence $\textcircled{2}$ implies that

$$\boxed{\rho_t + \nabla \cdot (\rho \vec{u}) = 0.}$$

b) We will now consider Lagrangian coordinates $(\vec{x}(\vec{x}_0, t), t)$. We have

$$\begin{aligned} \frac{d}{dt} \vec{x}(\vec{x}_0, t) &= \vec{u}(\vec{x}(\vec{x}_0, t), t) && \text{fluid velocity} \\ \rho(\vec{x}(\vec{x}_0, t), t) & && \text{density (mass/volume)} \\ p(\vec{x}(\vec{x}_0, t), t) & && \text{pressure} \\ \vec{F}(\vec{x}(\vec{x}_0, t), t) & && \text{body forces.} \end{aligned}$$

We begin the case where the gas is at equilibrium, where we assume the density is constant and equal to ρ_0 .

Let S be a ball of radius R in \mathbb{R}^3 , and let Ω be the region containing the fluid "particles" that were originally in S at a later time. That is, we want to use Lagrangian coordinates, so we follow the individual motion of each particle.

Let $\vec{n}(\vec{x}(t), t)$ denote the unit normal vector to Ω at time t and position $\vec{x}(t)$. Newton's 2nd Law states $\frac{d}{dt}$ (total momentum) = \sum Forces.

The time derivative of the total momentum of the fluid is given by

$$\frac{d}{dt} \iiint_S \rho_0 \vec{u}(\vec{x}(t), t) dV_s . \quad (3)$$

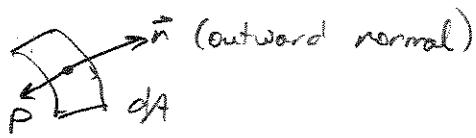
We can move the derivative through the integrals, since S does not depend on time and we are integrating over the volume and not over time. Thus (3) becomes

$$\begin{aligned} \iiint_S \rho_0 \frac{d}{dt} \vec{u}(\vec{x}(t), t) dV_s &\stackrel{\text{see below}}{=} \iiint_S \rho_0 \left(\nabla \vec{u} \cdot \frac{\partial \vec{x}}{\partial t} + \vec{u}_t \right) dV_s \\ &= \iiint_S \rho_0 \left[(\nabla \vec{u}) \cdot \vec{u} + \vec{u}_t \right] dV_s . \end{aligned}$$

$$(4) \quad \frac{d}{dt} \vec{u}(\vec{x}(t), t) = \frac{d}{dt} \begin{bmatrix} u_1[x(t), y(t), z(t), t] \\ u_2[x(t), y(t), z(t), t] \\ u_3[x(t), y(t), z(t), t] \end{bmatrix}$$

$$= \begin{bmatrix} \frac{\partial u_1}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial u_1}{\partial y} \frac{\partial y}{\partial t} + \frac{\partial u_1}{\partial z} \frac{\partial z}{\partial t} + \frac{\partial u_1}{\partial t} \\ \frac{\partial u_2}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial u_2}{\partial y} \frac{\partial y}{\partial t} + \frac{\partial u_2}{\partial z} \frac{\partial z}{\partial t} + \frac{\partial u_2}{\partial t} \\ \frac{\partial u_3}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial u_3}{\partial y} \frac{\partial y}{\partial t} + \frac{\partial u_3}{\partial z} \frac{\partial z}{\partial t} + \frac{\partial u_3}{\partial t} \end{bmatrix} = \begin{bmatrix} \nabla u_1 \cdot \frac{\partial \vec{x}}{\partial t} \\ \nabla u_2 \cdot \frac{\partial \vec{x}}{\partial t} \\ \nabla u_3 \cdot \frac{\partial \vec{x}}{\partial t} \end{bmatrix} + \begin{bmatrix} \frac{\partial u_1}{\partial t} \\ \frac{\partial u_2}{\partial t} \\ \frac{\partial u_3}{\partial t} \end{bmatrix} = \nabla \vec{u} \cdot \vec{u} + \vec{u}_t$$

The net forces acting on the fluid are due to pressure and external forces. If we look at a small "piece" of $\partial\Omega$, we have



Thus the force due to pressure on Ω is:

$$\iint_{\partial\Omega} p \hat{n} dA$$

The external forces are given by

$$\iiint_S \rho_0 \vec{F}(\vec{x}(z, t), t) dV_s$$

Thus the net force acting on the fluid is

$$\Sigma F = - \iint_{\partial\Omega} p \hat{n} dA + \iiint_S \rho_0 \vec{F}(\vec{x}(z, t), t) dV_s$$

$$\begin{aligned} \text{Now, } \iint_{\partial\Omega} p \hat{n} dA &= \begin{bmatrix} \iint_{\partial\Omega} p n_1 dA \\ \iint_{\partial\Omega} p n_2 dA \\ \iint_{\partial\Omega} p n_3 dA \end{bmatrix} = \begin{bmatrix} \iint_{\partial\Omega} p \vec{e}_1 \cdot \hat{n} dA \\ \iint_{\partial\Omega} p \vec{e}_2 \cdot \hat{n} dA \\ \iint_{\partial\Omega} p \vec{e}_3 \cdot \hat{n} dA \end{bmatrix} \xrightarrow{\text{divergence theorem}} \begin{bmatrix} \iiint_S \nabla \cdot p \vec{e}_1 dV \\ \iiint_S \nabla \cdot p \vec{e}_2 dV \\ \iiint_S \nabla \cdot p \vec{e}_3 dV \end{bmatrix} \\ &= \begin{bmatrix} \iiint_S p_x dV \\ \iiint_S p_y dV \\ \iiint_S p_z dV \end{bmatrix} = \iint_S \nabla p(\vec{x}(z, t), t) dV \end{aligned}$$

Thus Newton's 2nd Law implies

$$\iiint_S \rho_0 [\vec{u} \cdot (\nabla \vec{u}) + \vec{u}_e] dV_s = - \iiint_S \nabla p dV + \iiint_S \rho_0 \vec{F} dV_s \quad \textcircled{D}$$

The final step is to change coordinates from S to Ω in the integral on the left and the last integral on the right. When we do this, we have $\int_S g_0 dV_S = \int_{\Omega} g(\vec{x}(x, t), t) dV = \int_{\Omega} J dV_S$, where J denotes the determinant of the Jacobian of the transformation from S to Ω . This implies that $\rho_0 = \rho J$. Thus (4) becomes

$$\iiint_{\Omega} f(x, \vec{u}, \vec{u}_t) \rho dV = - \iiint_{\Omega} \nabla p dV + \iiint_{\Omega} \vec{F} \cdot \vec{\rho} dV$$

$$\Leftrightarrow \iiint_{\Omega} [\vec{u}_t + \vec{u} \cdot \nabla \vec{u}]_p + \nabla p - \vec{\rho} \cdot \vec{F} dV = 0$$

Since Ω was an arbitrary domain in \mathbb{R}^3 , Problem ② implies

$$\vec{u}_t + \vec{u} \cdot \nabla \vec{u} + \nabla p - \vec{\rho} \cdot \vec{F} = 0$$

$$\Leftrightarrow \boxed{\vec{u}_t + \vec{u} \cdot \nabla \vec{u} + \nabla p = \vec{\rho} \cdot \vec{F}}.$$

$$④ \quad \vec{E} = \frac{c \vec{r}}{\|\vec{r}\|^3} = \frac{c \langle x, y, z \rangle}{(x^2 + y^2 + z^2)^{3/2}}$$

- a) By computing the constant value of $\vec{E} \cdot \vec{n}$ of the sphere of radius R deduce that the flux integral

$$\iint \vec{E} \cdot \vec{n} dS = 4\pi c$$

$\|\vec{r}\|=R$

independently of R .

- b) Compute $\operatorname{div}(\vec{E}) = \nabla \cdot \vec{E}$ and show it is 0 for all $\vec{r} \neq \vec{0}$.

- c) Consider a sum of translations and scalings of the vector field \vec{E}' :

$$\vec{E}' = \frac{c_1 (\vec{r} - \vec{r}_1)}{\|\vec{r} - \vec{r}_1\|^3} + \dots + \frac{c_k (\vec{r} - \vec{r}_k)}{\|\vec{r} - \vec{r}_k\|^3}$$

Use the divergence theorem, linearity of divergence and flux integrals w.r.t. vector fields to show if Ω is an 3d domain

(with piecewise smooth $\partial\Omega$, so div. thm. applies), then

$$\iint_{\partial\Omega} \vec{F} \cdot \hat{n} dS = 4\pi(c_1 + \dots + c_k).$$

Soln:

a) For a sphere, the unit exterior normal is $\frac{\vec{r}}{\|\vec{r}\|}$. Thus

$$\vec{E} \cdot \hat{n} = \frac{c\vec{r}}{\|\vec{r}\|^3} \cdot \frac{\vec{r}}{\|\vec{r}\|} = \frac{c(\vec{r} \cdot \vec{r})}{\|\vec{r}\|^4} = \frac{c\|\vec{r}\|^2}{\|\vec{r}\|^4} = \frac{c}{\|\vec{r}\|^2} = \frac{c}{R^2}$$

Thus $\iint_{\|\vec{r}\|=R} \vec{E} \cdot \hat{n} dA = \iint_{\|\vec{r}\|=R} \frac{c}{R^2} dA = \frac{c}{R^2} \iint dA = \frac{c}{R^2} \cdot 4\pi R^2 = 4\pi c$

b) $\nabla \cdot \vec{E} = \frac{\partial E_1}{\partial x} + \frac{\partial E_2}{\partial y} + \frac{\partial E_3}{\partial z}$.

Now, $E_1 = \frac{cx}{(x^2+y^2+z^2)^{3/2}}$, so

$$\begin{aligned} \frac{\partial E_1}{\partial x} &= c \frac{(x^2+y^2+z^2)^{3/2} - x \cdot \frac{3}{2}(x^2+y^2+z^2)^{1/2} \cdot 2x}{(x^2+y^2+z^2)^3} = c \frac{\|\vec{r}\|^3 - 3x^2\|\vec{r}\|}{\|\vec{r}\|^6} \\ &= c \frac{\|\vec{r}\|^2 - 3x^2}{\|\vec{r}\|^5}. \end{aligned}$$

By symmetry, $\frac{\partial E_2}{\partial y} = c \frac{\|\vec{r}\|^2 - 3y^2}{\|\vec{r}\|^5}$ and $\frac{\partial E_3}{\partial z} = c \frac{\|\vec{r}\|^2 - 3z^2}{\|\vec{r}\|^5}$,

$$\begin{aligned} \text{so } \nabla \cdot \vec{E} &= c \frac{\|\vec{r}\|^2 - 3x^2}{\|\vec{r}\|^5} + c \frac{\|\vec{r}\|^2 - 3y^2}{\|\vec{r}\|^5} + c \frac{\|\vec{r}\|^2 - 3z^2}{\|\vec{r}\|^5} \\ &= c \frac{3\|\vec{r}\|^2 - 3(x^2+y^2+z^2)}{\|\vec{r}\|^5} = c \frac{3\|\vec{r}\|^2 - 3\|\vec{r}\|^2}{\|\vec{r}\|^5} = 0 \text{ for } \vec{r} \neq 0. \end{aligned}$$

c) We first note that $\nabla \cdot \vec{F} = \nabla \cdot \sum_{j=1}^k \vec{E}_j = \sum_{j=1}^k \nabla \cdot \vec{E}_j$, where

$$\vec{E}_j = \frac{c_j(\vec{r} - \vec{r}_j)}{\|\vec{r} - \vec{r}_j\|^3} \quad j = 1, 2, \dots, k.$$

By part b), $\nabla \cdot \vec{E}_j = 0$ everywhere except at \vec{r}_j ; because, if we let $\vec{u}_j = \vec{r} - \vec{r}_j$, we have

$$\vec{E}_j = \frac{c_j \vec{u}_j}{\|\vec{u}_j\|^3}, \text{ and } \nabla \cdot \vec{E}_j = 0 \text{ except where } \vec{u}_j = 0 \Leftrightarrow \vec{r} - \vec{r}_j = 0 \Leftrightarrow \vec{r} = \vec{r}_j,$$

$$\text{Thus } \iiint_{\Omega} \nabla \cdot \vec{F} dV = \iiint_{\Omega} \sum_{j=1}^k \nabla \cdot \vec{E}_j dV = \sum_{j=1}^k \iiint_{\Omega} \nabla \cdot \vec{E}_j dV.$$

$$\text{Now, we know that } \nabla \cdot \vec{E}_j = 0 \text{ if } \vec{r} \neq \vec{r}_j. \text{ Thus } \iiint_{\Omega} \nabla \cdot \vec{E}_j dV$$

can be found by integrating over a small ball around \vec{r}_j , as long as this ball is contained within Ω . Choose $\varepsilon > 0$ so that

$B(\vec{r}_j, \varepsilon) \cap B(\vec{r}_i, \varepsilon) = \emptyset$ for $i, j = 1, \dots, k$ where $i \neq j$ and so that $B(\vec{r}_j, \varepsilon) \subset \Omega$ for $j = 1, \dots, k$. (This is assuming that all of the \vec{r}_j 's are in Ω .) Then

$$\iiint_{\Omega} \nabla \cdot \vec{F} dV = \sum_{j=1}^k \iiint_{\Omega} \nabla \cdot \vec{E}_j dV = \sum_{j=1}^k \iiint_{B(\vec{r}_j, \varepsilon)} \nabla \cdot \vec{E}_j dV$$

$$\text{By part a), } \iiint_{B(\vec{r}_j, \varepsilon)} \nabla \cdot \vec{E}_j = 4\pi c_j.$$

$$\text{Therefore } \iiint_{\Omega} \nabla \cdot \vec{F} dV = \sum_{j=1}^k \iiint_{B(\vec{r}_j, \varepsilon)} \nabla \cdot \vec{E}_j = \sum_{j=1}^k 4\pi c_j = 4\pi \sum_{j=1}^k c_j. \quad (5)$$

$$\text{By the divergence theorem, } \iiint_{\Omega} \nabla \cdot \vec{F} dV = \iint_{\partial \Omega} \vec{F} \cdot \vec{n} dS$$

$$\text{Thus, by (5), } \iint_{\partial \Omega} \vec{F} \cdot \vec{n} dS = 4\pi \sum_{j=1}^k c_j = 4\pi(c_1 + \dots + c_k). \quad \blacksquare$$