

Math 2250-1

Wed 9/7

§2.2

Recall

- autonomous 1st order DE

- equilibrium sol'n's

- stability
unstable

- asymptotically stable

additional examples: find equilibria; discuss stability

- $\frac{dx}{dt} = x^4 - x^2$

- $\frac{dx}{dt} = \cos x$

- did anyone think of an example of a 1st order autonomous DE with an equilibrium sol'n which is stable, but not asymptotically stable?

①

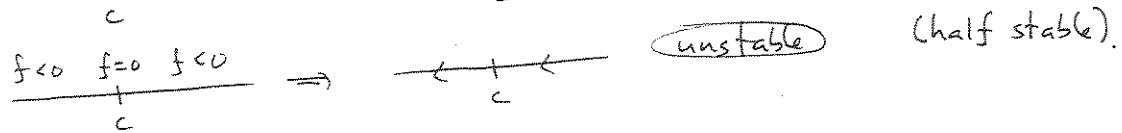
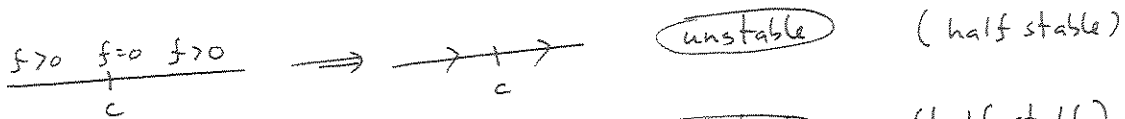
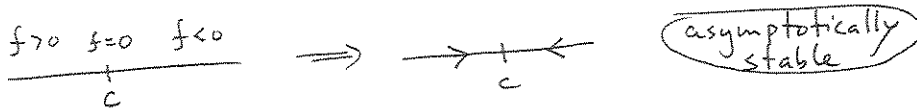
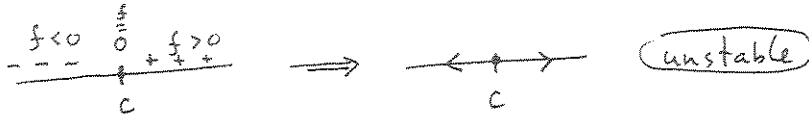
Theorem Consider the autonomous differential equation

$$\frac{dx}{dt} = f(x)$$

with f and $\frac{\partial f}{\partial x}$ continuous. (so local existence and uniqueness theorem holds).

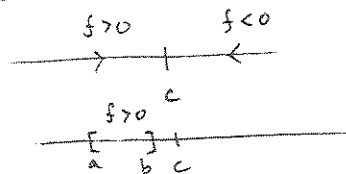
(let $f(c) = 0$ so $x(t) \equiv c$ is an equilibrium sol'n.

Suppose c is an isolated zero of f , i.e. c is in an open interval I ,
 $c \in I$ and f has no other zeroes in I . Then



you can prove this theorem with Calculus!!
 (want to try?)

e.g. consider the second case



f cont; $f > 0$ on subinterval $[a, b]$

$\Rightarrow f \geq \delta > 0$ on $[a, b]$

(extreme value thm from calculus, f attains its minimum).

$\Rightarrow x'(t) \geq \delta$ as long as $x(t) \in [a, b]$

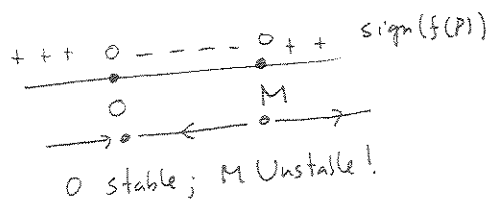
$\Rightarrow x(t)$ stays in this interval for time interval at most $\frac{b-a}{\delta}$

Applications

doomsday extinction:

$$\frac{dP}{dt} = aP^2 - bP \quad a, b > 0$$

$$= kP(P-M) \quad \begin{matrix} k=a \\ -kM=b \end{matrix}$$



e.g. if $\beta(t)$ (fertility rate) $\sim P$

(e.g. herd roams in a fixed area and mates randomly upon meeting opposite-sex mate)

then $B(t) = aP^2$;

perhaps $D(t) = -bP$.

If $0 < P_0 < M$ then $\lim_{t \rightarrow \infty} P(t) = 0$ (so in real life, extinction)

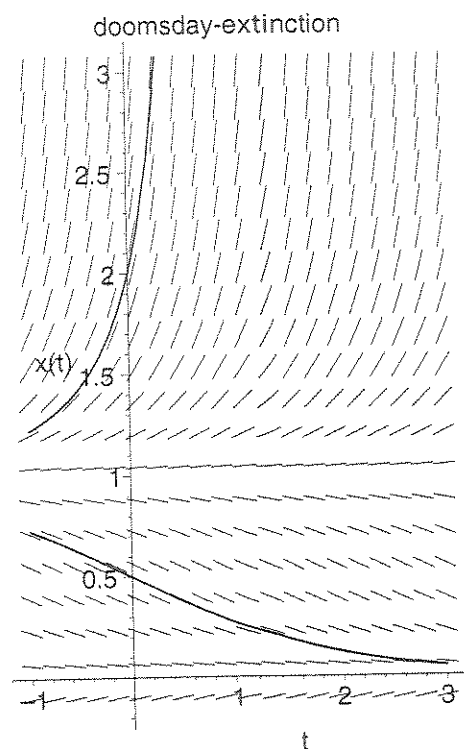
If $P_0 > M$ then $\exists t_1 < \infty$ s.t. $\lim_{t \rightarrow t_1} P(t) = +\infty$ (doomsday!)

example

$$\begin{cases} \frac{dx}{dt} = x(x-1) \\ x(0) = 2 \end{cases}$$

Find the time of doomsday.

(ans $t = \ln 2$!)



harvesting a logistic population (e.g. a fishery).

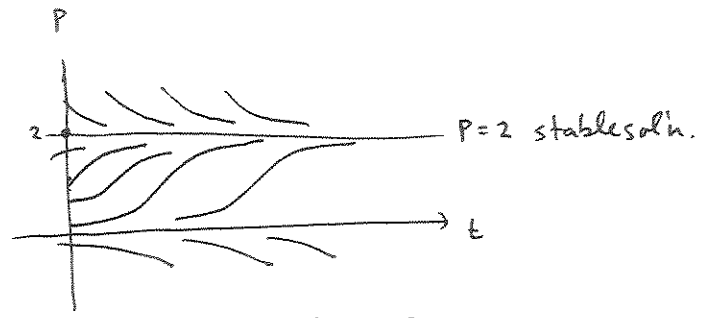
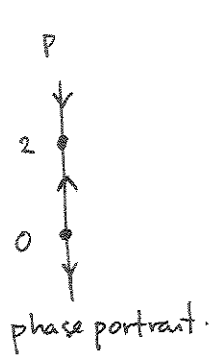
$$\frac{dP}{dt} = \underbrace{aP - bP^2}_{\text{logistic}} - \underbrace{h}_{\text{constant rate harvesting}}$$

See examples 4-6 §2.2
 one could also analyze "constant effort harvesting"
 by considering instead a term $-hP$, see e.g. §2.2 #23.

for computational simplicity
 take $a=2, b=1$

Case 0 no harvesting

$$P'(t) = 2P - P^2 = P(2 - P)$$



if $P_0 > 0, P(t) \rightarrow 2$.
 (units could be millions of fish, e.g.)

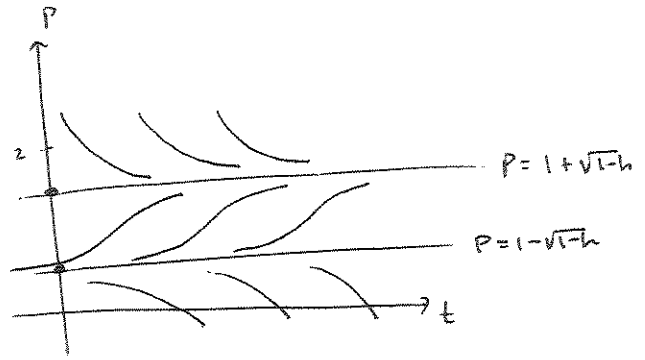
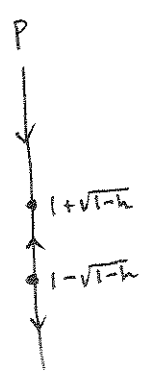
with harvesting:

$$P'(t) = 2P - P^2 - h = -(P^2 - 2P + h) = -(P - P_1)(P - P_2)$$

$$P_1, P_2 = \frac{2 \pm \sqrt{4 - 4h}}{2} = 1 \pm \sqrt{1 - h}$$

Case 1: subcritical harvesting

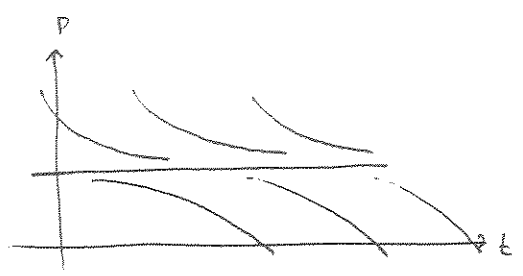
$$0 < h < 1$$



Case 2 Critical harvesting

$h = 1$

$P'(t) = -(P-1)^2$

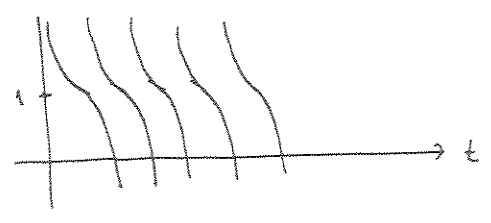


Case 3 Overharvesting

$h > 1$

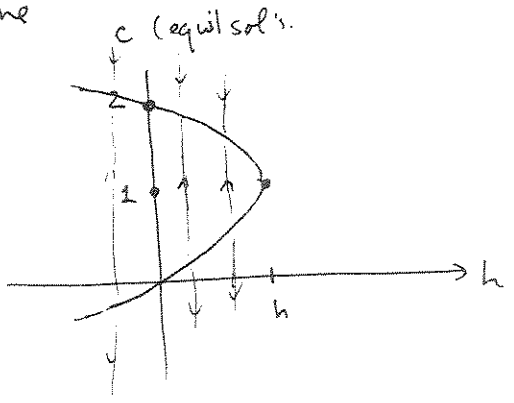
complex roots.

$P'(t) = -(P^2 - 2P + h)$
 $= -[(P-1)^2 + (h-1)]$
 < 0



this model gives a plausible explanation for why many fisheries collapse: if $h < 1$ but near 1, and if something perturbs the system a little bit (e.g. slightly increased fishing pressure, a big storm, etc.), you could be confronted with "sudden" unexpected fishery collapse.

"bifurcation diagram" of equilibrium solutions in the $h-c$ plane



(you can fill in the vertical phase portraits as I indicated. negative h might model constant rate fish stocking...)