

Math 2250-1

Tuesday 10/4

↳ 4.1-4.3 cont'd; start 4.4

Vocabulary/concept review:

linear combination of $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k$:span $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k\}$: $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k$ linearly independent" linearly dependentvector space V subspace $W \subset V$, where V is a vector space (subspace is not the same as subset).

Then finish pages 4-5 of Monday's notes, exercises 5-9

Exercise 10: Characterize all possible subspaces of \mathbb{R}^3 - there are 4 types

n exercises 9-10, we used (& understood):

Theorem: Let $\vec{v}_1, \dots, \vec{v}_k$ be vectors in \mathbb{R}^n (or V).
Then $\text{span}\{\vec{v}_1, \dots, \vec{v}_k\}$ is a subspace of V

check

$\alpha)$ if $\vec{v} = c_1\vec{v}_1 + \dots + c_k\vec{v}_k$ and $\vec{u} = d_1\vec{v}_1 + \dots + d_k\vec{v}_k$ are both in $\text{span}\{\vec{v}_1, \dots, \vec{v}_k\}$
then $\vec{v} + \vec{u} = (c_1 + d_1)\vec{v}_1 + \dots + (c_k + d_k)\vec{v}_k \in \text{span}\{\vec{v}_1, \dots, \vec{v}_k\}$.

& $\beta)$ $t\vec{v} = tc_1\vec{v}_1 + tc_2\vec{v}_2 + \dots + tc_k\vec{v}_k \in \text{span}\{\vec{v}_1, \dots, \vec{v}_k\}$. ■

Exercise 6 is a special case of

Theorem Let $A_{m \times n}$. The solution set to the homogeneous matrix equation $A\vec{x} = \vec{0}$
i.e. $W := \{\vec{x} \in \mathbb{R}^n \text{ s.t. } A\vec{x} = \vec{0}\}$ is a subspace of \mathbb{R}^n

check

$\alpha)$ if $\vec{x}, \vec{y} \in W$, then $A\vec{x} = \vec{0}$ and $A\vec{y} = \vec{0}$. Thus $A(\vec{x} + \vec{y}) = A\vec{x} + A\vec{y} = \vec{0} + \vec{0} = \vec{0}$

$\beta)$ if $\vec{x} \in W$, then $A\vec{x} = \vec{0}$ so
 $A(c\vec{x}) = cA\vec{x} = c\vec{0} = \vec{0}$ so $\vec{x} + \vec{y} \in W$.

so $c\vec{x} \in W$. ■

Definition : If $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k$ span a subspace W
 and if $\vec{v}_1, \dots, \vec{v}_k$ are linearly independent,
 then $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k\}$ is called a basis for W .

Definition : The number of vectors in a basis for a subspace W is
 called the dimension of W

Exercise 11

What are the dimensions of the 4 subspace types in exercise 10?

Exercise 12 Find a basis for the solution space to $A\vec{x} = \vec{0}$, for the $A_{4 \times 6}$ at right. Explain why your basis spans the solution space. Verify that your basis is linearly independent (The solution set to $A\vec{x} = \vec{0}$ is called the nullspace of A .)

```

[> with(LinearAlgebra):
> A := Matrix(4, 6, [1, 2, 0, 1, 1, 2,
                    2, 4, 1, 4, 1, 7,
                    -1, -2, 1, 1, -2, 1,
                    -2, -4, 0, -2, -2, -4]);
A :=
| 1 2 0 1 1 2 | 0
| 2 4 1 4 1 7 | 0
| -1 -2 1 1 -2 1 | 0
| -2 -4 0 -2 -2 -4 | 0
> ReducedRowEchelonForm(A):
| 1 2 0 1 1 2 | 0
| 0 0 1 2 -1 3 | 0
| 0 0 0 0 0 0 | 0
| 0 0 0 0 0 0 | 0
]

```

Exercise 13: Another natural subspace associated to the matrix $A_{4 \times 6}$ in Ex. 12, is the span of the 6 columns. This is a subspace of \mathbb{R}^4 (called the column space). How many different bases for this subspace can you find, using only (some) of the columns of the original matrix?

Hint: if you begin with all 6 columns and successively discard columns which are dependent on the ones you have left, you won't decrease their span.... keep doing this until you have an independent spanning set.

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[> with(LinearAlgebra):
> A := Matrix(4, 6, [1, 2, 0, 1, 1, 2,
                    2, 4, 1, 4, 1, 7,
                    -1, -2, 1, 1, -2, 1,
                    -2, -4, 0, -2, -2, -4]);
                    A :=
                    | 1  2  0  1  1  2 | 0
                    | 2  4  1  4  1  7 | 0
                    | -1 -2  1  1 -2  1 | 0
                    | -2 -4  0 -2 -2 -4 | 0
> ReducedRowEchelonForm(A);
                    | 1  2  0  1  1  2 | 0
                    | 0  0  1  2 -1  3 | 0
                    | 0  0  0  0  0  0 | 0
                    | 0  0  0  0  0  0 | 0
[>

```