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Math 2250-3

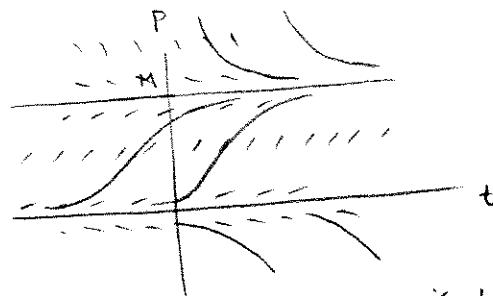
Friday 9/10

I (believe) I have reserved PC Lab 1735 in MMC labs
(Marriott basement)

10-12 Saturday morning, if you want to work on Maple project with trouble shooter (me) present.

- Finish Logistic model of U.S. Population (Wed. notes)

const solns $P=0, P=M$
these are called equilibrium solutions



isoclines are horizontal lines

$$\text{sign } \frac{dP}{dt} : \begin{array}{c} \cdots \\ \cdots \\ \cdots \end{array} \begin{array}{c} 0 \\ + \\ + \\ + \end{array} \begin{array}{c} M \\ - \\ - \end{array} \begin{array}{c} \cdots \\ \cdots \\ \cdots \end{array}$$

$$\text{sign } kP(M-P)$$

deduce that $P \nearrow$ or \searrow as follows

we call $P=M$ a stable equilibrium because

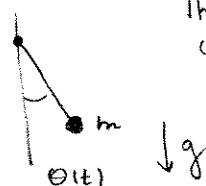
if P_0 is near M then $P(t)$ stays near M for all $t > 0$
(in fact M is asymptotically stable, i.e. if P_0 is near enough to M , then $\lim_{t \rightarrow \infty} P(t) = M$.)

we call $P=0$ anunstable equilibrium because it is not true

that if P_0 is near enough to 0 then $P(t)$ stays close to zero.

The notion of equilibrium solutions and stability is used throughout DE's - for example, consider a rigid rod pendulum, for which all θ are possible.

There are 2 equilibrium configurations, one is stable & one is unstable.



logistic:

$$\text{fertility rate } \beta = \beta_0 - \beta_1 P, \quad \text{morbidity } \delta = \delta_0 - \delta_1 P, \quad \frac{dP}{dt} = \beta - \delta \quad \text{leads to } \frac{dP}{dt} = aP^2 - bP = kP(M-P).$$

doomsday / extinction is a related population model, with wildly different dynamics:

Assume: an individual's probability of reproducing is proportional to the probability they encounter an individual of the opposite sex (think alligators).

$\beta = kP$

Individuals cover territory of certain size, so prob of meeting partner is proportional to population density. If creatures live in fixed area pop density is prop to P

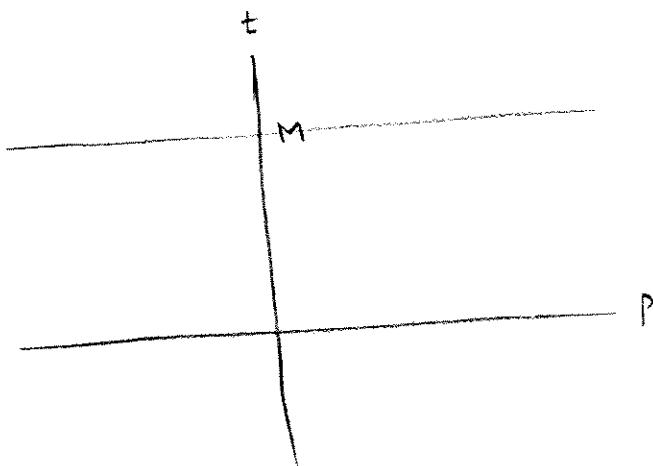
slope field.

If $\beta = kP$ and $\delta = \delta_0$

get

$$\frac{dP}{dt} = kP - \delta_0$$

$$\frac{dP}{dt} = kP^2 - \delta_0 P \\ = kP(P-M)$$



sign $\frac{dP}{dt}$:

++	0	--	0	++
0			M	

dynamics

→ → →	← ← ←	→ → →
0		M

What are the equilibrium sol's?
Which are stable? unstable?

one of your HW problems is to solve this DE,
(2.1 #33)

Find

$$P(t) = \frac{MP_0}{P_0 + (M-P_0)e^{-Mkt}}$$

from which you can analytically verify
what the slope field predicts.

General language & notions

If DE has form

$$\boxed{\frac{dx}{dt} = f(x)}$$

it is called autonomous

solutions which are constant in time are called equilibrium solutions

[if $x(t) = x_0$ is const soltn then

$$\frac{dx}{dt} = 0 \quad \text{and} \quad \frac{dx}{dt} = f(x) = f(x_0) \quad \text{so } x_0 \text{ is a root of } f(x),$$

and visa versa]

examples

$$\frac{dx}{dt} = kx(M-x) \quad \text{logistic}$$

$$\frac{dx}{dt} = kx(x-M) \quad D/Ext$$

$$\frac{dx}{dt} = k(A-x) \quad \text{Newton's Law of cooling}$$

$$\frac{dx}{dt} = x^3 - x$$

$$\frac{dx}{dt} = \sin x$$

Let c be an equilibrium soltn for $\frac{dx}{dt} = f(x)$

If, for each $\varepsilon > 0$ there exists a $\delta > 0$ s.t.

$$|x_0 - c| < \delta \text{ implies } |x(t) - c| < \varepsilon \text{ for all } t > 0$$

for solns to IVP with $x(0) = x_0$

then c is stable equil. (solutions starting close to c stay close to c)

else c is unstable equil.

If c is stable equil. & there exists $\delta > 0$ st.

$$|x_0 - c| < \delta \text{ implies } \lim_{t \rightarrow \infty} x(t) = c \text{ then}$$

c is asymptotically stable

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example Find and classify equilibria for

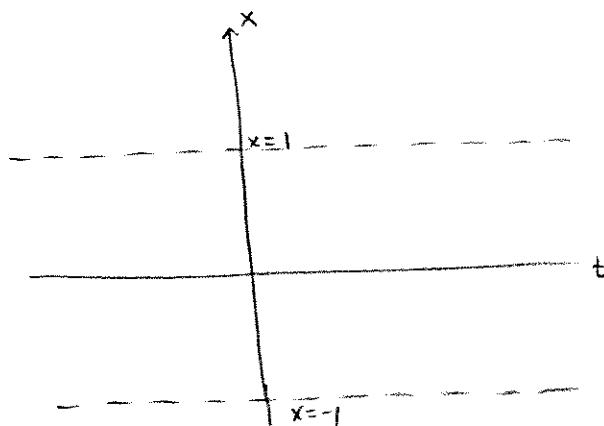
$$\begin{aligned}\frac{dx}{dt} &= x^2 - x^4 \\ &= x^2(1-x^2) \\ &= x^2(1-x)(1+x)\end{aligned}$$

$$\text{equil: } x = 0, 1, -1$$



$$\text{sign } \frac{dx}{dt} \quad \text{---} \circ \text{++} \circ \text{++} \circ \text{---}$$

stability?



slope field and solution graphs?