

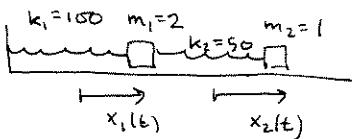
Math 2250-3

Wednesday 11/24

- Finish Glucose-Insulin model from Monday's notes. Then do springs:

Spring systems §7.4 (We will finish this section Monday)

Example 1 p 431.



$$2x_1'' = -100x_1 + 50(x_2 - x_1)$$

$$1x_2'' = -50(x_2 - x_1)$$

$$\begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x_1'' \\ x_2'' \end{bmatrix} = \begin{bmatrix} -100 & 50 \\ 50 & -50 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$M\ddot{x} = K\ddot{x}$$

in general, with  $n$  masses and up to  $n+1$  springs,  $M$  &  $K$  are  $n \times n$  matrices

$$\Rightarrow \ddot{x} = A\ddot{x} \quad \text{where } A = M^{-1}K.$$

$$\begin{bmatrix} x_1'' \\ x_2'' \end{bmatrix} = \begin{bmatrix} -75 & 25 \\ 50 & -50 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \quad \text{in this example.}$$

What is the dimension of the solution space?  
(Careful!) {

Look for solutions

$$\vec{x}(t) = \cos \omega t \vec{v} \neq \sin \omega t \vec{v}, \quad \text{based on previous experience}$$

$$x' = -\omega \sin \omega t \vec{v}$$

$$x'' = -\omega^2 \cos \omega t \vec{v}$$

$$A\vec{x} = \cos \omega t A\vec{v}$$

must have

$$A\vec{v} = -\omega^2 \vec{v}$$

$\vec{v}$  an eigenvector of  $A$   
with eval  $\lambda = -\omega^2$ .

- hope  $A$  has  $n$  lin ind events.

Each event gives 2 l.i. solns  $\cos \omega t \vec{v}, \sin \omega t \vec{v}$

$\Rightarrow 2n$  lin ind. solns

$\Rightarrow$  basis.

HW for Wed Dec 1

7.3 3, 4, 6, 13, 14, 25, 30, 32, 37 (postponed from this week)

7.4 2, 3, 8, 13, 14, 16, 17, 18

So, find general soltn to

$$\begin{bmatrix} x_1'' \\ x_2'' \end{bmatrix} = \begin{bmatrix} -7s & 2s \\ 50 & -50 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}.$$

Do you get

$$\vec{x}(t) = (c_1 \cos st + c_2 \sin st) \begin{bmatrix} 1 \\ 2 \end{bmatrix} + (c_3 \cos 10t + c_4 \sin 10t) \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

Explain what this solution means physically.  
 If you force this spring system, what angular frequencies for the forcing cosine function would induce resonance?

Now do forced oscillations:

$$M\ddot{\mathbf{x}}'' = K\ddot{\mathbf{x}} + \vec{b} \cos \omega t$$

or  $\ddot{\mathbf{x}}'' = A\ddot{\mathbf{x}} + \vec{F}_0 \cos \omega t$        $\vec{F}_0 = M^{-1}\vec{b}$

try  $\ddot{\mathbf{x}}_p = \vec{c} \cos \omega t$  [assuming  $\omega$  is not one of the natural angular frequencies]

$$\ddot{\mathbf{x}}_p'' = \vec{c} (-\omega^2 \cos \omega t)$$

$$\begin{aligned} \text{want} &= A\vec{c} \cos \omega t + \vec{F}_0 \cos \omega t \\ &= (A\vec{c} + \vec{F}_0) \cos \omega t \end{aligned}$$

$$-\omega^2 \vec{c} = A\vec{c} + \vec{F}_0$$

$$-\vec{F}_0 = A\vec{c} + \omega^2 I\vec{c}$$

$$-\vec{F}_0 = (A + \omega^2 I)\vec{c}$$

$$\vec{c} = (A + \omega^2 I)^{-1}(-\vec{F}_0)$$

(32) page  
433

trouble when  $\omega^2 = -2$

since  $A - 2I$  is sing!

### example 3

$$\ddot{\mathbf{x}}'' = \begin{bmatrix} -75 & 25 \\ 50 & -50 \end{bmatrix} \ddot{\mathbf{x}} + \begin{bmatrix} 0 \\ 50 \end{bmatrix} \cos \omega t$$

$$\ddot{\mathbf{x}}_p = \vec{c} \cos \omega t$$

$$-\omega^2 \vec{c} \cos \omega t = \begin{bmatrix} -75 & 25 \\ 50 & -50 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} \cos \omega t + \begin{bmatrix} 0 \\ 50 \end{bmatrix} \cos \omega t$$

$$\begin{bmatrix} -\omega^2 c_1 \\ -\omega^2 c_2 \end{bmatrix} \cos \omega t$$

$$\begin{bmatrix} 0 \\ -50 \end{bmatrix} = \begin{bmatrix} \omega^2 - 75 & 25 \\ 50 & \omega^2 - 50 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix}$$

$$c_1 = \frac{\begin{vmatrix} 0 & 25 \\ -50 & \omega^2 - 50 \end{vmatrix}}{(\omega^2 - 75)(\omega^2 - 50) - 50 \cdot 25}$$

$$c_1 = \frac{1250}{(\omega^2 - 25)(\omega^2 - 100)}$$

$$c_2 = \frac{50(\omega^2 - 75)}{(\omega^2 - 25)(\omega^2 - 100)}$$

Interpret!?