

Math 2250-3
Wed & Dec.

Final exam: Tuesday Dec 14, 1-3 p.m.
here.

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Review session: Fri Dec 10, 12:55-1:45
here

also, office hours Monday LCB 204
9:40-10:30
12:55-1:45

Exam is comprehensive:

- 15-20% { 1.1-1.5 1st order DE's
2.1-2.3 applications, equilibria & stability
- 15-25% { 3.1-3.6 matrix algebra & determinants
4.1-4.5, 4.7 vector space concepts
- 15-25% { 5.1-5.6 linear DE's & spring applications
- 10-20% { 6.1 eigenvalues & eigenvectors
- 15-25% { 7.1-7.4 linear systems of DE's; tank & spring systems
- 15-20% { 10.1-10.4 Laplace transforms; applications to DE's & DE systems

↑
possible percentages/topic

Analytic solution methods for DE's & systems of DE's

1st order DE's: linear, separable

higher order linear DE's: general soltn = $x_H + x_p$,

how to find x_H , x_p for constant coeff DE's,
use of Euler's formula for complex exponentials,
applications to mass-spring problems

eigenvalue, eigenvector methods, + matrix computations to find $\vec{x}_p(t)$ for

$$\frac{d\vec{x}}{dt} = A\vec{x} + \vec{f}(t)$$

$$\frac{d^2x}{dt^2} = Ax + \cos t \vec{c}$$

applications to tank & mass-spring systems.

Laplace transforms to solve linear DE's or DE systems. → You will get zeroes of the book covers, i.e. basic Laplace transforms and integrals.

Modeling: springs, spring systems
compartmental analysis (tanks)
population, velocity models, chptr 2

Geometric meaning for soltns to DE's & systems of DE's (and resulting "theorems").
slope fields, phase portraits, equilibrium soltns, stability
tangent vector fields (57.1)
existence/uniqueness for 1st order DE's or DE systems, or nth order DE's
dimension of solution space for homogeneous DE's or DE systems

Auxiliary tools

Linear algebra

new vocabulary, vector spaces, (in)dependence, span, dim, examples, etc.

solving linear systems, matrices, row, matrix algebra, A^{-1} , det's, etc.

evals & evecs

general sol'tn to $L(x) = b$ when L is a linear operator

Laplace transform (def, methods e.g. partial fractions, translation, etc.)
also, use in solving linear IVP's)

If we have time for some "fun":

Convolution

$$f * g(t) := \int_0^t f(\tau)g(t-\tau) d\tau \stackrel{\substack{\tilde{\tau} = t-\tau \\ d\tilde{\tau} = -d\tau}}{=} \int_0^t f(t-\tilde{\tau})g(\tilde{\tau})d\tilde{\tau} = g * f(t)$$

Laplace transform convolution

Theorem (see text page 604 for proof)

$$\mathcal{L}\{f * g\}(s) = F(s)G(s)$$

example $F(s) = G(s) = \frac{1}{s} = \mathcal{L}\{1\}$.

$$1 * 1(t) = \int_0^t 1 \cdot 1 d\tau = t$$

$$\mathcal{L}\{1 * 1\} = \mathcal{L}\{t\}(s) = \frac{1}{s^2} = \frac{1}{s} \cdot \frac{1}{s} \checkmark$$

example

$$(\sin * \cos)(t) = \int_0^t (\sin \tau) \cos(t-\tau) d\tau$$

$$= \int_0^t \sin \tau (\cos t \cos \tau + \sin t \sin \tau) d\tau$$

$$= \cos t \int_0^t \sin \tau \cos \tau d\tau + \sin t \int_0^t \sin^2 \tau d\tau$$

$u = \sin \tau, du = \cos \tau d\tau$
 $\sin^2 \tau = \frac{1 - \cos 2\tau}{2}$

$$= \cos t \left(\frac{1}{2} \sin^2 t \right) + \sin t \left[\frac{1}{2} t - \frac{\sin 2t}{4} \right]$$

$$= \frac{1}{2} t \sin t$$

so $\mathcal{L}\left\{ \frac{1}{2} t \sin t \right\}(s) = \left(\frac{1}{1+s^2} \right) \left(\frac{s}{1+s^2} \right) = \frac{s}{(1+s^2)^2}$

| $f(t)$ | $F(s)$ |
|---|---|
| 1 | $\frac{1}{s}$ |
| t | $\frac{1}{s^2}$ |
| t^n | $\frac{n!}{s^{n+1}} \quad n \in \mathbb{N}$ |
| e^{at} | $\frac{1}{s-a}$ |
| $\cos kt$ | $\frac{s}{s^2+k^2}$ |
| $\sin kt$ | $\frac{k}{s^2+k^2}$ |
| $\cosh kt$ | $\frac{s}{s^2-k^2}$ |
| $\sinh kt$ | $\frac{k}{s^2-k^2}$ |
| $f'(t)$ | $sF(s) - f(0)$ |
| $f''(t)$ | $s^2F(s) - sf(0) - f'(0)$ |
| etc. | |
| $\int_0^t f(\tau) d\tau$ | $\frac{1}{s}F(s)$ |
| $t f(t)$ | $-F'(s)$ |
| $t^2 f(t)$ | $F''(s)$ |
| etc. | |
| $\frac{f(t)}{t}$ | $\int_s^\infty F(\tau) d\tau$ |
| $t \cos kt$ | $\frac{(s^2-k^2)}{(s^2+k^2)^2}$ |
| $\frac{1}{2k} t \sin kt$ | $\frac{s}{(s^2+k^2)^2}$ |
| $\frac{1}{2k^3} (\sin kt - kt \cos kt)$ | $\frac{1}{(s^2+k^2)^2}$ |
| $t e^{at}$ | $\frac{1}{(s-a)^2}$ |
| $u(t-a)$ | e^{-as}/s |
| $u(t-a)f(t-a)$ | $e^{-as}F(s)$ |
| $e^{at}f(t)$ | $F(s-a)$ |
| $e^{at} \cos kt$ | $\frac{s-a}{(s-a)^2+k^2}$ |
| $e^{at} \sin kt$ | $\frac{k}{(s-a)^2+k^2}$ |
| $f * g(t)$ | $F(s)G(s)$ |

analogous

analogous

today

example With convolution, can get soltn formulas
in spring problems, for any forcing fun.

$$\begin{cases} x'' + x = f(t) \\ x(0) = x_0 \\ x'(0) = v_0 \end{cases}$$

$\omega_0 = 1$, natural period is 2π

If $f(t)$ is periodic, we expect resonance if period is 2π . (and only if).

Are we right?

\downarrow

\downarrow

$$s^2 X(s) - s x_0 - v_0 + X(s) = F(s)$$

$$X(s)(s^2 + 1) = s x_0 + v_0 + F(s)$$

$$X(s) = \frac{s x_0 + v_0}{s^2 + 1} + \frac{1}{s^2 + 1} F(s)$$

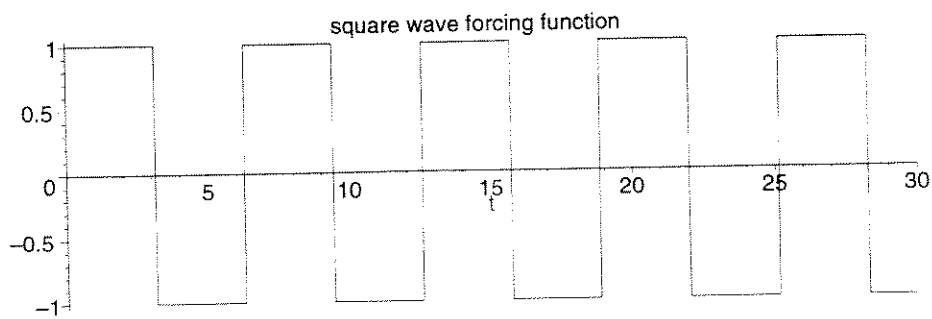
$$\text{so, } x(t) = x_0 \cos t + v_0 \sin t + \underbrace{f * \sin(t)}_{\int_0^t \sin(t-\tau) f(\tau) d\tau}$$

Now, let's play

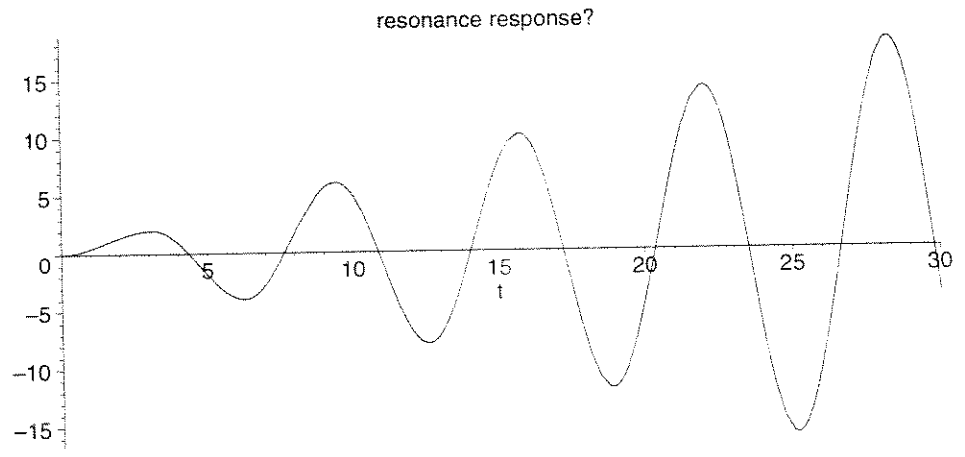
"Guess the resonance" game.

Math 2250-3
Wednesday December 8, 2004
Guess the resonance game

```
> with(plots):with(inttrans):
> f:=t->-1+2*sum((-1)^n*Heaviside(t-n*Pi),n=0..10);
> plot(f(t),t=0..30,color=black,title='square wave forcing
function');
```



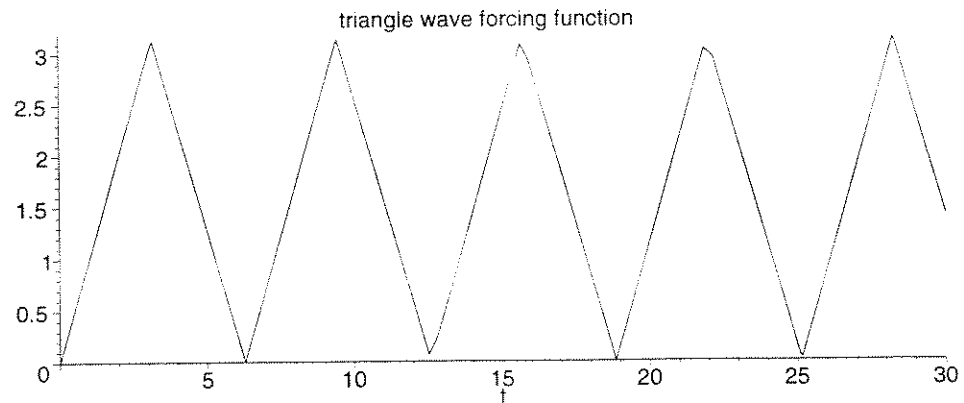
```
> x:=t->int(sin(t-tau)*f(tau),tau=0..t);
> plot(x(t),t=0..30,color=black,title='resonance response?');
```



```
> g:=t->int(f(u),u=0..t);
#this should be a triangle wave...
```

$$g := t \rightarrow \int_0^t f(u) du$$

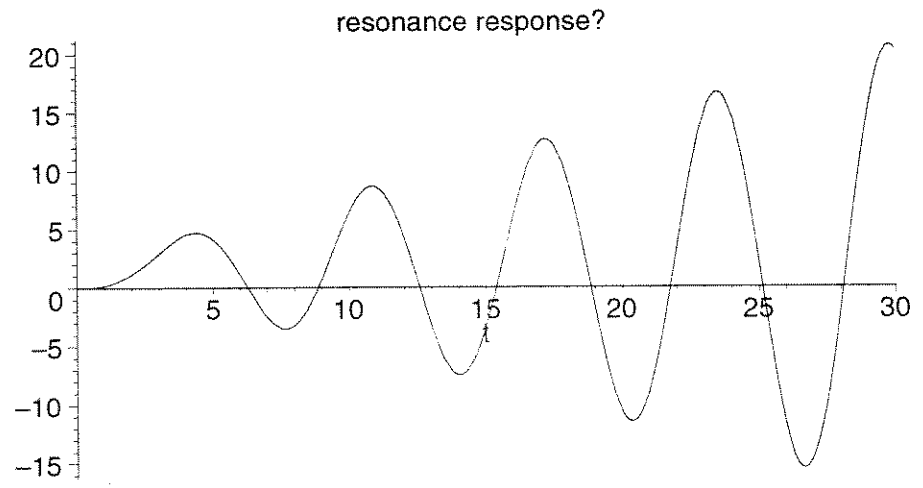
```
> plot(g(t),t=0..30,color=black, title='triangle wave forcing
function');
```



```
> y:=t->int(sin(t-tau)*g(tau),tau=0..t);
```

$$y := t \rightarrow \int_0^t \sin(t-\tau) g(\tau) d\tau$$

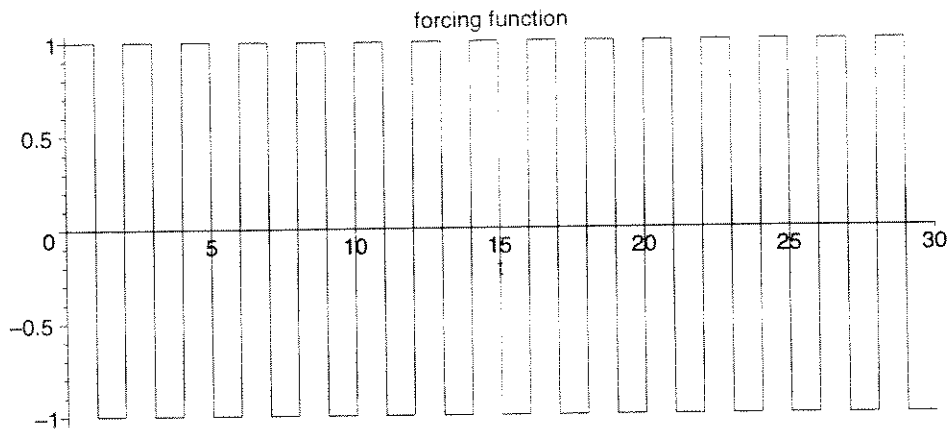
```
> plot(y(t),t=0..30,color=black, title='resonance response?');
```



```

> h:=t->-1+2*sum((-1)^n*Heaviside(t-n),n=0..30);
      h := t → -1 + 2 ⎛ ∑n=030 (-1)n Heaviside(t-n) ⎞
> plot(h(t),t=0..30,color=black, title='forcing function');

```

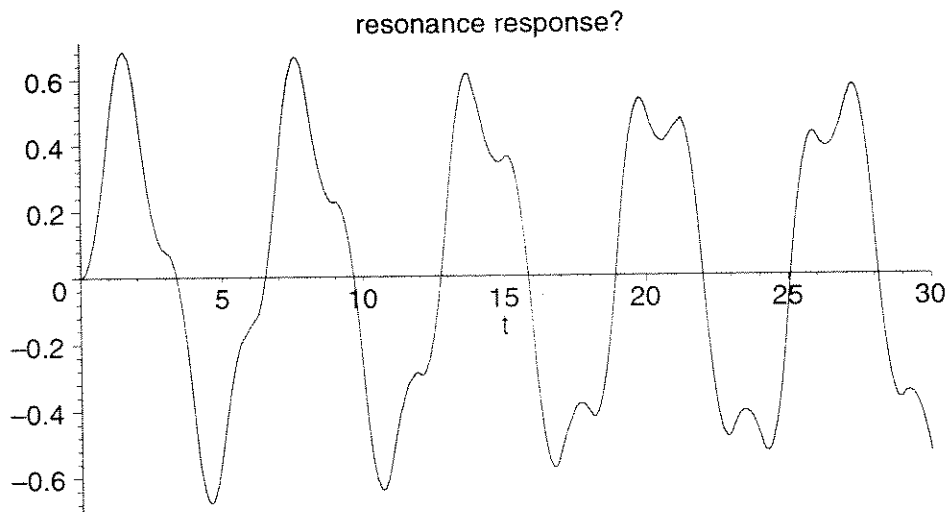


```

> z:=t->int(sin(t-tau)*h(tau),tau=0..t);
plot(z(t),t=0..30,color=black,title='resonance response?');

```

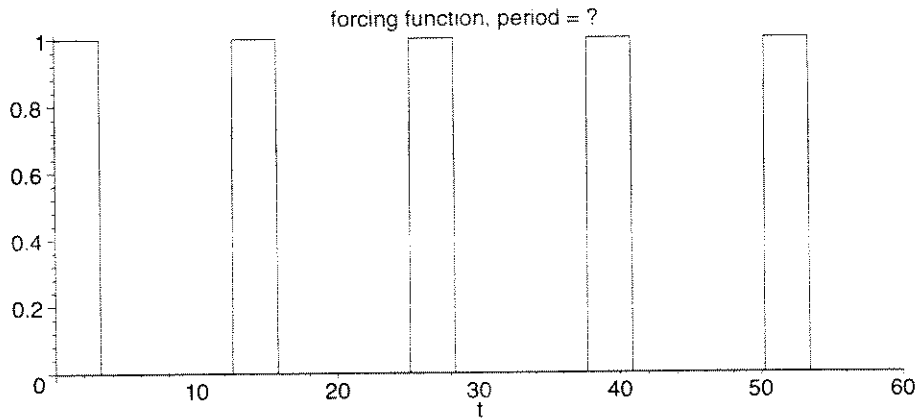
$$z := t \rightarrow \int_0^t \sin(t-\tau) h(\tau) d\tau$$



```
> k:=t->sum(Heaviside(t-4*Pi*n)-Heaviside(t-4*Pi*n-Pi),
n=0..5);
```

$$k := t \rightarrow \sum_{n=0}^5 (\text{Heaviside}(t - 4n\pi) - \text{Heaviside}(t - 4n\pi - \pi))$$

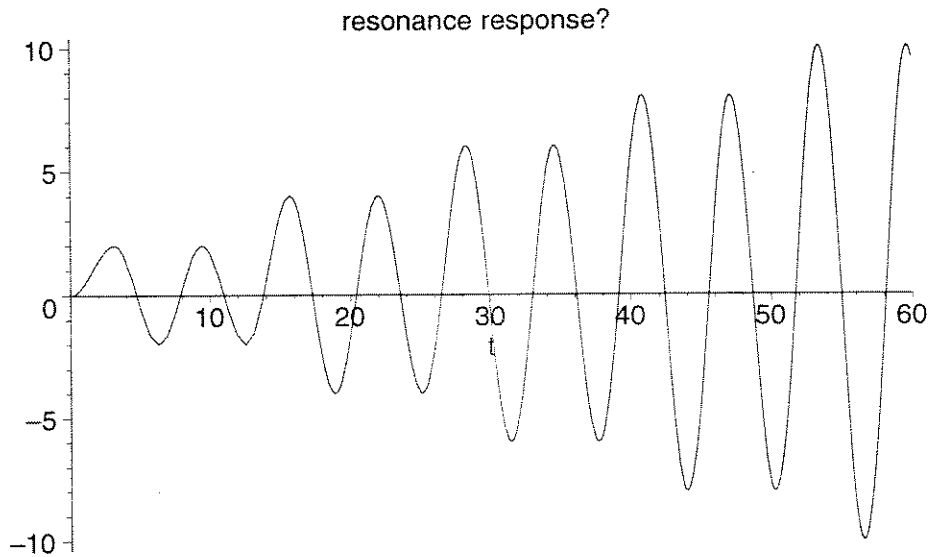
```
> plot(k(t),t=0..60,color=black,title='forcing function, period =
?');
>
```



```
> w:=t->int(sin(t-tau)*k(tau),tau=0..t);
```

$$w := t \rightarrow \int_0^t \sin(t - \tau) k(\tau) d\tau$$

```
> plot(w(t),t=0..60,color=black,title='resonance response?');
```



Hey, what happened?