Name	Class Time

#### Math 2280 Extra Credit Problems Chapter 4 S2019

Submitted work. Please submit one stapled package per chapter. Kindly label problems **Extra Credit**. Label each problem with its corresponding problem number, e.g., Xc4.1-8. Please attach this printed sheet to simplify your work.

### Problem XcL3.1. (Numerical Solutions)

You may submit this problem only for score increases on numerical solutions 2.4 to 2.6.

Solve symbolically by chapter 1 methods the initial value problem  $y' = 2xy^2$ , y(0) = 1. Do an answer check in maple or by hand. Answer:  $y = 1/(1 - x^2)$ . This problem has no numerical work!

#### Problem XcL3.2. (Numerical Solutions)

You may submit this problem only for score increases on numerical solutions 2.4 to 2.6. This problem counts as three (3) problems.

Solve  $y' = 2xy^2$ , y(0) = 1 numerically for the value of y(0.5) using (1) Euler's method, (2) Heun's method and (3) the RK4 method. Use step size h = 0.1. Include computer code and a print of the data. Report the answers in a table for x-values 0, 0.1, 0.2, 0.3, 0, 4, 0.5.

#### Problem XcL4.1. (Numerical Solutions)

You may submit this problem only for score increases on numerical solutions 2.4 to 2.6.

Solve symbolically by chapter 1 methods the initial value problem  $y' = e^{-y}$ , y(0) = 0. Do an answer check in maple or by hand. Answer:  $y = \ln(1+x)$ . This problem has no numerical work!

#### Problem XcL4.2. (Numerical Solutions)

You may submit this problem only for score increases on numerical solutions 2.4 to 2.6. This problem counts as three (3) problems.

Solve  $y' = e^{-y}$ , y(0) = 0 numerically for the value of y(1.0) using (1) Euler's method, (2) Heun's method and (3) the RK4 method. Use step size h = 0.001. Include a computer code appendix in the report, but do not print the data. Report the answers in a table for x-values 0, 0.2, 0, 4, 0.6, 0.8, 1.0. Include the percentage error  $E = 100|\ln(2) - y(1.0)|/|\ln(2)|$  in your report, one error report for each of the three methods.

#### Problem Xc4.1-8. (Transform to a first order system)

Use the position-velocity substitution  $u_1 = x(t)$ ,  $u_2 = x'(t)$ ,  $u_3 = y(t)$ ,  $u_4 = y'(t)$  to transform the system below into vector-matrix form  $\mathbf{u}'(t) = A\mathbf{u}(t)$ . Do not attempt to solve the system.

$$x'' - 2x' + 5y = 0$$
,  $y'' + 2y' - 5x = 0$ .

#### Problem Xc4.1-20a. (Dynamical systems)

Prove this result for system

$$\begin{aligned}
 x' &= ax + by, \\
 y' &= cx + dy.
 \end{aligned}$$

**Theorem**. Let  $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$  and define  $\mathbf{trace}(A) = a + d$ . Then  $p_1 = -\mathbf{trace}(A)$ ,  $p_2 = \det(A)$  are the coefficients in the determinant expansion

$$\det(A - rI) = r^2 + p_1 r + p_2$$

and x(t) and y(t) in equation (??) are both solutions of the differential equation  $u'' + p_1 u' + p_2 u = 0$ .

# Problem xC4.1-20b. (Solve dynamical systems)

(a) Apply the previous problem to solve

$$x' = 2x - y,$$
  
$$y' = x + 2y.$$

(b) Use first order methods to solve the system

$$\begin{array}{rcl}
x' & = & 2x & - & y, \\
y' & = & & 2y.
\end{array}$$

## Problem Xc4.2-12. (General solution answer check)

(a) Verify that 
$$\mathbf{x}_1(t) = e^{3t} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$
 and  $\mathbf{x}_2(t) = e^{2t} \begin{pmatrix} 1 \\ -2 \end{pmatrix}$  are solutions of  $\mathbf{x}' = A\mathbf{x}$ , where

$$A = \left( \begin{array}{cc} 4 & 1 \\ -2 & 1 \end{array} \right).$$

- (b) Apply the Wronskian test  $\det(\mathbf{aug}(\mathbf{x}_1,\mathbf{x}_2)) \neq 0$  to verify that the two solutions are independent.
- (c) Display the general solution of  $\mathbf{x}' = A\mathbf{x}$ .