Chapters 1,2. Sample Problem 7.

[a) Let
$$t_1 = 1.413$$
, $t_2 = 2.98$. Use $at^2+bt+c = v(t)$ for $t = 0$, t_1 , t_2 to obtain The system

$$\begin{cases}
a.o^2 + b.o + c = 50 \\
a.t_1^2 + b.t_1 + c = 0 \\
a.t_2^2 + bt_2 + c = -45
\end{cases}$$
Then $c = 50$. No 3×3 by term reduces to a 2×2 by term

$$\begin{cases}
a t_1^2 + b t_1 = -50 \\
a t_2^2 + b t_2 = -95
\end{cases}$$

$$\begin{cases}
a + b/t_1 = -50/t_1^2 & \text{mul}(1, 1/t_1^2) \\
a t_2^2 + b t_2 = -95
\end{cases}$$

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$$\begin{cases}
a + b/t_1 = -50/t_1^2 & \text{mul}(1, 1/t_1^2) \\
a t_2^2 + b t_2 = -95 \\
t_1^2 & \text{when } t_3 = t_2 - t_2^2
\end{cases}$$
Then $b = \frac{1}{t_2 t_1} \left(\frac{-50 t_2}{t_1} + 95 \frac{t_1}{t_2} \right) = \frac{-38.54760463}{t_1}$
The example gives evidence for why technology is used on systems of equations. For 2 -digit accuracy, it is less systems of equations. For 2 -digit accuracy, and quite fast with a calculator.

- (b) Substitution gives $2at+b=-32-p(at^2+bt+c)$, Nen t=0 implies b=-32-pc. Calculator gives $\rho=(-32-b)/c=0.1309520926\cong0.131$
 - (c) $W = aguil Sol + \frac{c_1}{integ factor} = \frac{-32}{p} + \frac{c_1}{e^{pt}}$, Then W(0)=50implies $C_1 = 50 + 32/p$.
 - (d) A good plot is | v(t)-w(t)| on 0 \(\pm \text{t\xi} \). It shows max error of 0-3. typo: v(t) above should be z(t)

Chapters 1,2. Sample Problem 8.

System
$$\begin{cases} -\frac{1}{6} \times_{1} + \frac{1}{6} \times_{2} = 0 \\ -\frac{1}{6} \times_{1} - \frac{1}{2} \times_{2} = 0 \\ -\frac{1}{6} \times_{1} - \frac{1}{2} \times_{2} = 0 \end{cases}$$
has diagnostical matrix equal to
$$\begin{pmatrix} -\frac{1}{6} & 0 & \frac{1}{6} & 0 \\ \frac{1}{6} & -\frac{1}{3} & 0 & 0 \\ 0 & \frac{1}{3} & -\frac{1}{6} & 0 \end{pmatrix}$$

$$\begin{pmatrix} -\frac{1}{6} & 0 & \frac{1}{6} & 0 \\ -\frac{1}{6} & -\frac{1}{3} & 0 & 0 \\ 0 & \frac{1}{3} & -\frac{1}{6} & 0 \end{pmatrix}$$

$$\begin{pmatrix} -1 & 0 & 1 & 0 \\ 0 & 2 & -1 & 0 \\ 0 & 2 & -1 & 0 \end{pmatrix}$$

$$\begin{pmatrix} -1 & 0 & 1 & 0 \\ 0 & 2 & -1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\begin{pmatrix} -1 & 0 & 1 & 0 \\ 0 & 2 & -1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\begin{pmatrix} -1 & 0 & 1 & 0 \\ 0 & 2 & -1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\begin{pmatrix} -1 & 0 & 1 & 0 \\ 0 & -2 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\begin{pmatrix} -1 & 0 & 1 & 0 \\ 0 & -2 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\begin{pmatrix} -1 & 0 & 1 & 0 \\ 0 & 2 & -1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\begin{pmatrix} -1 & 0 & -1 & 0 \\ 0 & 2 & -1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & -1 & 0 \\ 0 & 1 & -\frac{1}{2} & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & -1 & 0 \\ 0 & 1 & -\frac{1}{2} & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

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$$\begin{pmatrix} 1 & 0 & -1 & 0 \\ 0 & 1 & -\frac{1}{2} & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & -1$$

Onswer
$$\begin{cases} x_1 = t_1 \\ x_2 = \frac{1}{2}t_1 \\ x_3 = t_1 \end{cases} - \infty \angle t_1 \angle \infty$$

$$\begin{cases} x_1 = 2c \\ x_2 = c \\ x_3 = 2c \end{cases}$$