

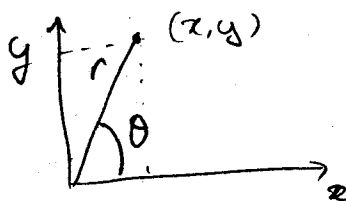
# § 4 PDE in polar and cylindrical coordinates

## • Polar coordinates

$$\begin{cases} x = r \cos \theta \\ y = r \sin \theta \end{cases} \Leftrightarrow \begin{cases} r^2 = x^2 + y^2 \\ \tan \theta = \frac{y}{x} \end{cases}$$

$$\theta = \tan^{-1} \frac{y}{x} + k\pi,$$

where  $k$  depends on  $x$  and  $y$ .



$$\Delta u = \frac{\partial^2 u}{\partial r^2} + \frac{1}{r} \frac{\partial u}{\partial r} + \frac{1}{r^2} \frac{\partial^2 u}{\partial \theta^2}$$

(all terms have same units as  $r^{-2}$ ).

is the representation of Laplacian in polar coordinate.

Deriving is long and tedious but it depends only on using chain rule and knowing derivatives such as:

$$r = \sqrt{x^2 + y^2} \rightarrow \begin{cases} \frac{\partial r}{\partial x} = \frac{x}{\sqrt{x^2 + y^2}} = \cos \theta \\ \frac{\partial r}{\partial y} = \frac{y}{\sqrt{x^2 + y^2}} = \sin \theta \end{cases}$$

$$\theta = \tan^{-1} \frac{y}{x} \rightarrow \begin{cases} \frac{\partial \theta}{\partial x} = \frac{1}{1 + (y/x)^2} \left( -\frac{y}{x^2} \right) = -\frac{y}{r^2} = -\frac{\sin \theta}{r} \\ \frac{\partial \theta}{\partial y} = \frac{1}{1 + (y/x)^2} \frac{1}{x} = \frac{x}{r^2} = \frac{\cos \theta}{r} \end{cases}$$

$$\frac{\partial^2 r}{\partial x^2} = \frac{\partial}{\partial x} (\cos \theta) = -\frac{\partial \theta}{\partial x} \sin \theta = \frac{\sin^2 \theta}{r}$$

$$\frac{\partial^2 r}{\partial y^2} = \frac{\partial}{\partial y} (\sin \theta) = \frac{\partial \theta}{\partial y} \cos \theta = \frac{\cos^2 \theta}{r}$$

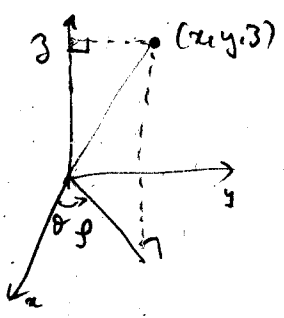
$$\frac{\partial^2 \theta}{\partial x^2} = \frac{\partial}{\partial x} \left( -\frac{\sin \theta}{r} \right) = -\frac{\partial}{\partial x} \left( \frac{\sin \theta}{r} \right) = -\frac{\partial}{\partial x} \left( \frac{1}{r} \right) \sin \theta - \frac{\partial}{\partial x} \left( \frac{1}{r} \right) \cos \theta$$

$$\begin{aligned} &= -2 \frac{\cos \theta \sin \theta}{r^2} \\ \frac{\partial^2 \theta}{\partial y^2} &= \frac{\partial}{\partial y} \left( \frac{\cos \theta}{r} \right) = \frac{\partial}{\partial y} (\cos \theta) \frac{1}{r} + \frac{\partial}{\partial y} \left( \frac{1}{r} \right) \cos \theta \\ &= -2 \frac{\cos \theta \sin \theta}{r^2} \end{aligned}$$

(these are included to practice with changes of coordinate, see p195 for more details)

• Cylindrical coordinates

$$\begin{cases} x = \rho \cos \phi \\ y = \rho \sin \phi \\ z = z \end{cases}$$



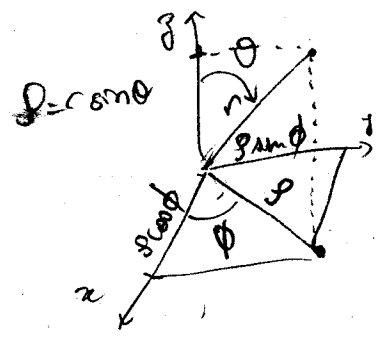
In cartesian coordinates:  $\Delta u = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2}$

using polar form of Laplacian:

$$\Delta u = \frac{\partial^2 u}{\partial \rho^2} + \frac{1}{\rho} \frac{\partial u}{\partial \rho} + \frac{1}{\rho^2} \frac{\partial^2 u}{\partial \phi^2} + \frac{\partial^2 u}{\partial z^2}$$

• Spherical coordinates

$$\begin{cases} x = r \cos \phi \sin \theta \\ y = r \sin \phi \sin \theta \\ z = r \cos \theta \end{cases}$$



we have:  
 $r^2 = x^2 + y^2 + z^2$

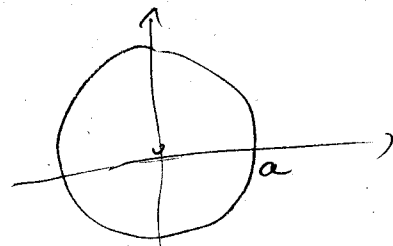
$$\Delta u = \frac{\partial^2 u}{\partial r^2} + \frac{2}{r} \frac{\partial u}{\partial r} + \frac{1}{r^2} \left( \frac{\partial^2 u}{\partial \theta^2} + \frac{1}{\tan \theta} \frac{\partial u}{\partial \theta} + \frac{1}{\sin^2 \theta} \frac{\partial^2 u}{\partial \phi^2} \right)$$

Derivation involves using Laplacian polar form on xy-plane and z-plane, where rho is projection of (x, y, z) onto (x, y) plane.

see p 137. We are not going to cover §5 so we won't use this too much in this class.

## § 4.2 Vibrations of a circular membrane (radially symm)

We study vibrations of a circular membrane (drum) clamped on edges i.e.  $u(a, \theta, t) = 0$ , where  $u(r, \theta, t)$  = displacement of membrane from equilibrium.



These are governed by the 2D wave equation:

$$u_{tt} = c^2 \Delta u$$

which in polar coordinates (better adapted to this problem than cartesian)

$$u_{tt} = c^2 \left( \frac{\partial^2 u}{\partial r^2} + \frac{1}{r} \frac{\partial u}{\partial r} + \frac{1}{r^2} \frac{\partial^2 u}{\partial \theta^2} \right)$$

We consider first the case where:

initial shape  $f(r, \theta) = f(r)$

initial velocity  $g(r, \theta) = g(r)$

(radially symm)

Because of the symmetry of the problem,  $u(r, \theta) = u(r)$   
 $\Rightarrow \frac{\partial u}{\partial \theta} = 0$

Thus we are left with the simplified PDE:

$$\begin{cases} u_{tt} = c^2 (u_{rr} + \frac{1}{r} u_r) \\ u(a, t) = 0 \\ u(r, 0) = f(r) \\ u_t(r, 0) = g(r) \end{cases}$$

Use separation of variables:  $u(r, t) = R(r)T(t)$

$$RT'' = c^2 (R''T + \frac{1}{r} R'T)$$

$$\Rightarrow \frac{T''}{c^2 T} = \frac{1}{R} (R''T + \frac{1}{r} R'T) = -\frac{\lambda^2}{r} = \text{const}$$

otherwise no time periodic sol!

We get 2 equations to solve:

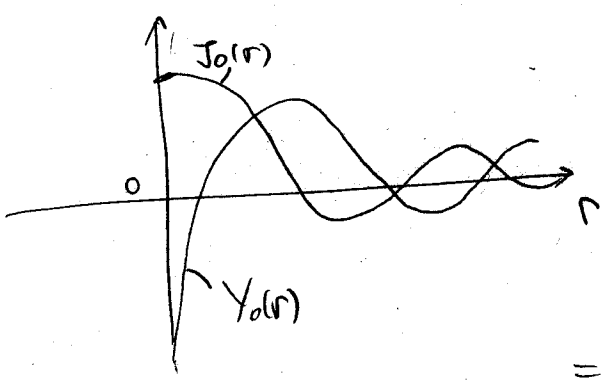
$$(1) \begin{cases} rR'' + R' + \lambda^2 rR = 0 \\ R(a) = 0 \end{cases} \quad (2) \begin{cases} T'' + c^2 \lambda^2 T \\ \dots \end{cases}$$

(1) Bessel equation of order 0 (parameter form)  
 2nd order linear eq  $\Rightarrow$  we need 2 lin indep sol to describe all possible solutions.

$J_0(\lambda r)$  Bessel function of order 0 of first kind  
 $Y_0(\lambda r)$  2nd

Sol to (1) is

$$R(r) = c_1 J_0(\lambda r) + c_2 Y_0(\lambda r)$$



$r \rightarrow 0 \Rightarrow Y_0(r) \rightarrow -\infty$   
 Since  $|R(0)| < \infty$   
 we must have  $c_2 = 0$

$$\Rightarrow R(r) = c_1 J_0(\lambda r), \text{ take } c_1 = 1 \neq 0$$

$$R(a) = c_1 J_0(\lambda a) = 0$$

$\lambda a$  must be a root of Bessel fun  $J_0$ .

Let  $\alpha_1 < \alpha_2 < \dots < \alpha_n < \dots$  be zeros of  $J_0$

then  $\lambda = \lambda_n = \frac{\alpha_n}{a}, \quad n = 1, 2, \dots$

and  $R_n(r) = J_0\left(\frac{\alpha_n}{a} r\right), \quad n = 1, \dots$

(analogous to the ones for Sine Series expansion:

we solve  $\sin(\lambda L) = 0 \Leftrightarrow \lambda L = n\pi$   
 $\lambda_n = \frac{n\pi}{L}$

and analogy does not stop here!

Then we go back to (2) and write its solution:

$$T_n(t) = A_n \cos\left(\frac{c \alpha_n}{a} t\right) + B_n \sin\left(\frac{c \alpha_n}{a} t\right)$$

→ By construction:

$$\boxed{u_n(r, t) = R_n(t) T_n(t) = \left( A_n \cos\left(\frac{c \alpha_n}{a} t\right) + B_n \sin\left(\frac{c \alpha_n}{a} t\right) \right) J_0\left(\frac{\alpha_n}{a} r\right)}$$

$n = 1, 2, \dots$

solves DE and so does:

$$u(r, t) = \sum_{n=1}^{\infty} \left( A_n \cos\left(\frac{c \alpha_n}{a} t\right) + B_n \sin\left(\frac{c \alpha_n}{a} t\right) \right) J_0\left(\frac{\alpha_n}{a} r\right)$$

What about B.C.?

$$f(r) = u(r, 0) = \sum_{n=1}^{\infty} A_n J_0\left(\frac{\alpha_n}{a} r\right) = \text{Bessel Series Expansion} \quad (*)$$

Looks a lot like Fourier series expansion, and it relies on  $J_0\left(\frac{\alpha_n}{a} r\right)$  being orthogonal in the inner prod:

$$(u, v) = \int_0^a u(r) v(r) r dr \quad \left( \text{compare to } (u, v) = \int_{-p}^p u(x) v(x) dx \right)$$

$$\text{and: } (J_0\left(\frac{\alpha_n}{a} r\right), J_0\left(\frac{\alpha_m}{a} r\right)) = \begin{cases} 0 & \text{if } n \neq m \\ \frac{a^2 J_1^2(\alpha_n)}{2} & \text{if } n = m \end{cases}$$

thus: dotting by  $J_0\left(\frac{\alpha_n}{a} r\right)$  on both sides of (\*)

$$A_n = \frac{(f(r), J_0\left(\frac{\alpha_n}{a} r\right))}{(J_0\left(\frac{\alpha_n}{a} r\right), J_0\left(\frac{\alpha_n}{a} r\right))} = \frac{2}{a^2 J_1^2(\alpha_n)} \int_0^a f(r) J_0\left(\frac{\alpha_n}{a} r\right) r dr$$

here  $J_1(r) =$  Bessel fun of order 1 (available in matlab ...)